

FLOW LOOPS AND QUANTUM GROUPS

SUNGHYUK PARK

ABSTRACT. This paper connects two seemingly different ways of studying knots: quantum group invariants and the dynamics of Morse flows. For fibered knots, we define a two-variable series invariant by counting Morse flow loops in the complement. This dynamical series is conjectured to agree with the BPS q -series of the knot complement, which arises from Verma modules for quantum groups and encodes all colored Jones polynomials. We prove this correspondence for all braid-homogeneous knots.

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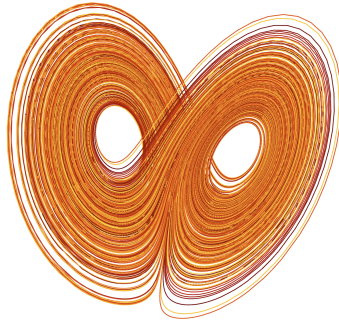


FIGURE 1. Lorenz system is a system of ODEs determining a three-dimensional flow. Every solution to the system eventually gets attracted to the set shown, called the Lorenz attractor.

1. INTRODUCTION

Dynamics is a subject with a long history, going back at least to Newtonian mechanics. It studies the long-term behavior of systems that evolve over time, such as the famous Lorenz system [Lor63] (Figure 1), which is an example of a three-dimensional flow. The dynamics of three-dimensional flows are particularly interesting, since their periodic orbits can be knotted in interesting ways. Birman and Williams [BW83a] showed that such knotted periodic orbits can be completely analyzed using certain branched surfaces known as *knot holders* (a.k.a. templates [GHS97]), which “hold” the knotted periodic orbits; the dynamics of three-dimensional flows can be encoded into the symbolic dynamics on knot holders.

Quantum topology, in contrast, studies knots and low-dimensional manifolds through invariants that are usually constructed using representation-theoretic tools. It emerged in the late 1980s, largely driven by the discovery of the Jones polynomial [Jon85] and its interpretation and generalization in terms of representation theory of quantum groups [RT90]. These representation-theoretic definitions of link polynomials are *diagrammatic* in that one associates a polynomial to each link diagram and then checks the invariance under Reidemeister moves.

In his lecture at the Hermann Weyl Symposium in 1987, Atiyah famously posed the following question:

Question 1.1 ([Ati88]). Is there an intrinsically three-dimensional definition of the Jones polynomial?

Witten later gave two remarkable answers to this question. First, in [Wit89], he interpreted the Jones polynomial in terms of the 3-dimensional topological quantum field theory now known as Chern–Simons theory, where it arises as the partition function of S^3 in the presence of a Wilson line defect supported on the link. Second, in [Wit12], he proposed a gauge-theoretic interpretation in terms of counting solutions to the Kapustin–Witten equations on $S^3 \times [0, \infty)$ with boundary conditions determined by the link.

These insights are among the most beautiful and influential in quantum topology and mathematical physics. At the same time, from the perspective of obtaining a direct and computable mathematical definition of the Jones polynomial, substantial difficulties remain. In Chern–Simons theory, the partition function is formulated in terms of path integrals,

for which a direct mathematical definition is still unavailable.¹ On the gauge-theoretic side, no rigorous mathematical definition is currently available for the count of solutions to the Kapustin–Witten equations, even for the unknot, and substantial analytical difficulties, including compactness, remain. This motivates the search for another answer to Question 1.1, one that is both intrinsically three-dimensional and computable.

The purpose of this article is to give such a *geometric* definition of quantum invariants for fibered links, using ideas from dynamics. This new bridge is motivated by ideas from topological string theory. Witten [Wit95] showed that Chern–Simons theory can be embedded in topological string theory, and Ooguri and Vafa [OV00] developed this picture further, predicting a relationship between quantum link invariants and open Gromov–Witten invariants. A rigorous mathematical formulation of this picture emerged only much later, when Ekholm and Shende [ES26] defined deformation-invariant counts of open holomorphic curves via skein-valued curve counting, culminating in a proof of the Ooguri–Vafa conjecture. This development is a crucial ingredient for the present work, but it does not by itself provide an independent way to compute quantum link invariants, since in practice the evaluation of these curve counts still relies on prior knowledge of the corresponding colored HOMFLYPT polynomials.

In [EGG⁺22], we proposed a related picture for knot complements, predicting that the corresponding open Gromov–Witten invariants recover the *BPS q -series* (a.k.a. the \widehat{Z} -invariant) for the knot complement [GM21, Par20, Par21], which in turn encodes all the colored Jones polynomials of the knot. For fibered links, this picture becomes especially concrete. In that case, the knot complement Lagrangian $M_K \subset T^*S^3$, diffeomorphic to $S^3 \setminus K$, can be shifted off the zero section $S^3 \subset T^*S^3$, so that the skein-valued count of holomorphic curves in $(T^*S^3, S^3 \sqcup M_K)$ gives a precise definition of these open Gromov–Witten invariants. In the Morse flow graph limit [Ekh07] (see also [ELPS25, Appendix A]), these holomorphic curves degenerate to Morse flow graphs, which in the present setting are Morse flow loops, i.e., periodic orbits of the Morse flow [CEL26]. What makes this picture computable is that the relevant GL_2 -quantum invariants are recovered from the GL_1 -skein-valued count of these flow loops, which depends only on their linking numbers. This is where ideas from dynamics enter, through tools such as knot holders.

Summary of main results. We first define an invariant of fibered knots coming from the GL_1 -skein-valued flow loop counts:

Theorem A. *For any fibered knot K , the GL_1 -skein-valued flow loop count*

$$\Phi_{S^3 \setminus K}(x, q) \in \mathbb{Z}[q^{\pm 1}][[x]]$$

is a well-defined knot invariant.

Remark 1.2. While we mainly work with fibered knots for simplicity, this invariant can be straightforwardly extended to fibered links. If K is a fibered link with s components, then the GL_1 -skein-valued flow loop count takes value in the completion of $\mathbb{Z}[q^{\pm 1}][x_1^{\pm 1}, \dots, x_s^{\pm 1}]$ with respect to the total x -degree, where x_1, \dots, x_s represent the homology classes in $H_1(S^3 \setminus K)$ corresponding to the positive meridians.

While this invariant is essentially the GL_1 -reduction of the skein-valued flow loop count considered in [CEL26], we provide an elementary proof of deformation invariance (independent of the skein-valued curve count of [ES26]) via bifurcation analysis in Appendix A.

¹There is a recent alternative approach using factorization homology; see [CFG26].

This GL_1 -skein-valued flow loop count is a mathematically precise version of the open Gromov-Witten invariants considered in [EGG⁺22]. In particular, the conjecture of [EGG⁺22] can be reformulated precisely as follows:

Conjecture 1.3. *For any fibered link K ,*

$$\Phi_{S^3 \setminus K} = \widehat{Z}_{S^3 \setminus K}.$$

Here, $\widehat{Z}_{S^3 \setminus K}$ on the right-hand side denotes the BPS q -series of $S^3 \setminus K$.² The mathematical definition of the BPS q -series is currently available for all braid-homogeneous links [Par21], or more generally, for all links admitting “nice” diagrams [Par22].³ In case of fibered links for which we do not currently have an independent definition of the right-hand side, the conjecture should be understood as saying that the flow loop count provides a resummation of the Melvin-Morton-Rozansky (MMR) expansion [Roz98, Roz99] of the colored Jones polynomials of K , in the sense of [GM21, Conj. 1.5]. In particular, Conjecture 1.3 would imply the following finiteness conjecture for MMR expansions of fibered knots:

Conjecture 1.4 ([Par21]). *For any fibered knot K , the coefficients of its MMR expansion*

$$\frac{1}{[n]} J_{K,n}(q) \Big|_{q=e^{\hbar}} \quad \begin{array}{l} \hbar \rightarrow 0, n \rightarrow \infty \\ \text{while } u := n\hbar \text{ fixed} \\ \widetilde{x} := e^u \end{array} \quad \frac{1}{\Delta_K(x)} + \sum_{d \geq 1} \frac{P_d(x)}{\Delta_K(x)^{2d+1}} \hbar^d, \quad P_d(x) \in \mathbb{Q}[x^{\pm 1}],$$

when expanded into a power series in x , which are a priori just in $\mathbb{Q}[[\hbar]]$, can be resummed into uniquely determined Laurent polynomials in $\mathbb{Z}[q^{\pm 1}]$.

Our main theorem settles Conjecture 1.3 for all braid-homogeneous knots:

Theorem B. *For any braid-homogeneous knot, Conjecture 1.3 is true.*

Since $\widehat{Z}_{S^3 \setminus K}$ encodes all the colored Jones polynomials of K via some change of variables, it immediately implies that the flow loop count $\Phi_{S^3 \setminus K}$ encodes all the colored Jones polynomials of K , hence giving an intrinsically three-dimensional geometric definition of these quantum link invariants.

While $\Phi_{S^3 \setminus K}$ counts flow loops in the complement $S^3 \setminus K$, the BPS q -series $\widehat{Z}_{S^3 \setminus K}$ is usually defined in terms of a state sum on a link diagram of K , using Verma modules of the quantum group $U_q(\mathfrak{sl}_2)$ [Par20, Par21]. As an intermediary step toward proving Theorem B, we show that braid group representations typically constructed using quantum groups can be recovered from these flow loop counts:

Theorem C. *The braid group representation on tensor powers of Verma modules can be obtained by counting flow loops.*

Organization of the paper. In Section 2, we define the skein-valued count of flow loops in fibered 3-manifolds and prove Theorem A. In Section 3, we explain how to actually count such flow loops in practice, using knot holders; this leads to a geometric state sum model on knot holders. In Section 4, we describe the braid group representation induced from these flow loop counts. We then prove Theorem C, showing that this braid group representation is

²Normalized here so that it starts with $1 + \dots$, by factoring out an overall monomial factor of the form $\pm q^{\dots} x^{\dots}$. See the end of Section 5 for the precise monomial.

³While it is not known whether all fibered links are nice, all fibered knots up to 12 crossings are known to be nice [OSSAS26].

equivalent to the one coming from tensor products of Verma modules. Finally, in Section 5, we prove our main theorem (Theorem B) showing that the flow loop count is equal to the BPS q -series, for all braid-homogeneous knots.

Future directions. We conclude the introduction by outlining some directions of research we plan to pursue in future work.

- The BPS q -series \widehat{Z} , as originally predicted from physics [GPV17, GPPV20, GM21], is expected to admit a categorification. The geometric definition of the BPS q -series in terms of flow loop count provides a promising approach to this problem: it suggests that there should be a Floer-type theory whose generators are these flow loops. It would be very interesting to construct such a homology theory.
- We can also add extra Wilson line defects along some link $L \subset S^3 \setminus K$, as in Theorem 2.8. The resulting two-variable series $\widehat{Z}_{S^3 \setminus K, L} \in \mathbb{Z}[q^{\pm 1}]((x))$ then counts not only flow loops but also flow lines starting and ending on L . This is the analog of the Jones polynomial of L , in $S^3 \setminus K$ instead of S^3 . A categorification of such a two-variable series would be the analog of Khovanov homology [Kho00] for links in $S^3 \setminus K$. When K is the unknot, this should specialize to the annular Khovanov homology (a.k.a. annular APS homology) [APS04].
- Extending down, there should be a dg- (or A_∞ -) category associated to marked fiber surfaces⁴, so that the categorical trace (i.e., Hochschild homology) of the monodromy autofunctor should recover the conjectural homology theory in the first bullet point above. It would be interesting to see if there is any connection to the one proposed in [CHT25].
- It would also be interesting to extend the results of this paper to non-fibered knots. In case of non-fibered knots, the circle-valued Morse function will necessarily have some critical points, so we need to count not just flow loops but also flow lines between those critical points. In terms of Lagrangians, this would mean shifting the knot complement Lagrangian M_K so that it intersects the zero section $S^3 \subset T^*S^3$ transversely at finitely points; see [DE25, Sec. 8.4]. The count of holomorphic curves in $(T^*S^3, S^3 \cup M_K)$ should then take a value in the “skein module of the intersecting Lagrangians $S^3 \cup M_K$.” Understanding such a skein module and identifying it with an appropriate two-variable power series ring would be the key steps in this direction.

Acknowledgements. I am indebted to Tobias Ekholm and Sergei Gukov for numerous inspiring conversations and discussions over the years.

This work was supported in part by Simons Foundation through Simons Collaboration on Global Categorical Symmetries.

2. SKEIN-VALUED COUNT OF FLOW LOOPS

In this section, we define the main object of this paper, the GL_1 -skein-valued count of flow loops. This section is highly inspired by a recent work [CEL26], as our count is nothing but the GL_1 -reduction of the count considered in that paper.

⁴Categorifying the object $Z(F)$ of the skein category discussed in Section 3.5.

2.1. General setup. Let K be a fibered knot, so that its complement admits a fibration $\pi : S^3 \setminus K \rightarrow S^1$, which is unique up to isotopy. Such a fibration can be viewed as a circle-valued Morse function on the knot complement. Accordingly, there is a nowhere-vanishing closed 1-form $\pi^*(d\theta)$ on $S^3 \setminus K$. Once a metric on $S^3 \setminus K$ is chosen, the closed 1-form can be dualized to a Morse flow vector field ξ_{Mor} , generating a Morse flow. We assume that the knot K is a sink of the Morse flow, by modifying the circle-valued Morse function near the boundary of $S^3 \setminus K$ if necessary. We also assume that all the periodic orbits of the Morse flow are nondegenerate (i.e., 1 is not an eigenvalue of the linearized return maps), by making a generic perturbation of the metric if necessary.

We are interested in counting periodic orbits of the Morse flow. A compactness argument shows that, for each period (i.e., a positive class in $H_1(S^3 \setminus K) \cong \mathbb{Z}$), there are only finitely many periodic orbits of that period. Let γ be a nondegenerate periodic orbit, and let ϕ_γ be the corresponding linearized return map. Then, there are three possibilities:

- (elliptic) Both eigenvalues of ϕ_γ are either inside or outside of the unit circle.
- (hyperbolic) One of the eigenvalues of ϕ_γ is inside the unit circle and the other one is outside the unit circle. There are two subcases of hyperbolic flow loops:
 - (positive hyperbolic) The two stable (and the two unstable) directions are preserved along γ , i.e., both eigenvalues of ϕ_γ are positive.
 - (negative hyperbolic) The two stable (and the two unstable) directions get permuted along γ , i.e., both eigenvalues of ϕ_γ are negative.

We say a periodic orbit is *primitive* if it is not a multiple cover of another orbit of smaller period. Let $\mathcal{O}_{\text{prim}}$ denote the set of primitive flow loops.

Consider the following count of flow loops:

$$(1) \quad \zeta_{S^3 \setminus K} := \prod_{\gamma \in \mathcal{O}_{\text{prim}}} w_\gamma \in \mathbb{Z}[[x]],$$

where x is the positive generator of $H_1(S^3 \setminus K)$,

$$w_\gamma := \begin{cases} 1 - [\gamma] & \text{if } \gamma \text{ is elliptic,} \\ \frac{1}{1-[\gamma]} = 1 + [\gamma] + [\gamma]^2 + \dots & \text{if } \gamma \text{ is positive hyperbolic,} \\ \frac{1}{1+[\gamma]} = 1 - [\gamma] + [\gamma]^2 - \dots & \text{if } \gamma \text{ is negative hyperbolic,} \end{cases}$$

and $[\gamma] \in H_1(S^3 \setminus K) \cong \mathbb{Z}$ is the corresponding homology class, so that $[\gamma] = x^{\deg \gamma}$ if $\deg \gamma$ denotes the period of γ . It follows from a well-known result of Hutchings–Lee [HL99] that this count agrees with the inverse⁵ Reidemeister torsion:

$$\zeta_{S^3 \setminus K} = \frac{1 - x}{\Delta_K(x)},$$

where $\Delta_K(x)$ is the Alexander polynomial⁶ of K , giving a dynamical definition of the Alexander polynomial. By simply expanding the product (1), we also get the following expression:

$$(2) \quad \zeta_{S^3 \setminus K} = \sum_{\gamma \in \mathcal{O}} (-1)^{e(\gamma) + \text{nh}(\gamma)} [\gamma],$$

⁵Inverse because our weight w_γ is the inverse of the one used in [HL99].

⁶Normalized here in such a way that the power series expansion of the right-hand side starts with $1 + \dots$.

where \mathcal{O} denotes the set of all multi-flow loops (i.e., with possibly multiple components) where the hyperbolic components are allowed to be multiply covered, while the elliptic components cannot be multiply covered, and $e(\gamma)$ (resp., $\text{nh}(\gamma)$) denotes the total number of elliptic (resp., negative hyperbolic) flow loops in γ .

The GL_1 -skein-valued count of flow loops $\Phi_{S^3 \setminus K}$ that we define below can be thought of as a q -deformation of this count $\zeta_{S^3 \setminus K}$. The basic idea is to count these flow loops in the GL_1 -skein module, by not only remembering their homology class but also how they link with each other.

2.2. Framing. In order to introduce framing on the flow loops, we choose a framing vector field ξ_{fr} (a.k.a. 4-chain vector field) similarly to [ELPS25, Sec. 9.3],

$$\xi_{\text{fr}} = \xi_{\text{Mor}} + \epsilon \xi_{\text{pert}},$$

by perturbing the Morse flow vector field with a perturbation vector field ξ_{pert} , which is tangent to each fiber surface and has simple zeros, for which the boundary of the fiber surface is a sink. The locus of the zeros of ξ_{pert} is a closed 1-chain $\ell_{\text{fr}} \subset S^3 \setminus K$, called the *framing line defect*, oriented in the direction of the Morse flow, with each component of ℓ_{fr} carrying a sign $\in \{\pm 1\}$ corresponding to the index of the zero of ξ_{pert} in each fiber surface. We call framing lines with sign $+1$ (resp., -1) elliptic (resp., hyperbolic).

As long as a flow loop $\gamma \in \mathcal{O}$ does not intersect ℓ_{fr} , the vector field ξ_{fr} is everywhere transverse to the tangent vectors of γ , so we can use it to give a framing on the oriented link γ . Note, since the tangent vectors of γ are parallel to ξ_{Mor} in this setup, this is equivalent to the framing on γ induced by ξ_{pert} . In case a flow loop $\gamma \in \mathcal{O}$ intersects ℓ_{fr} , we may arbitrarily homotope γ off the framing line defect to induce a framing on γ ; the relation (5) below ensures that the result is independent in the GL_1 -skein module with framing lines.

2.3. Skein modules. Our count of Morse flow loops will take a value in a completion of the GL_1 -skein module of $S^3 \setminus K$, twisted by framing lines along ℓ_{fr} , whose definition is given as follows.

Definition 2.1. Let Y be an oriented 3-manifold, and let $\ell \subset Y$ be an oriented link each of whose component carries a sign. The GL_1 -skein module $\text{Sk}_q^{\text{GL}_1}(Y, \ell)$ of Y with framing lines along ℓ is the $\mathbb{Z}[q^{\pm 1}]$ -module generated by framed, oriented links in $Y \setminus \ell$, modulo the following local relations (all shown in blackboard framing):

$$(3) \quad q^{-1} \begin{array}{c} \nearrow \\ \searrow \end{array} = \begin{array}{c} \curvearrowright \\ \curvearrowleft \end{array} = q \begin{array}{c} \nwarrow \\ \swarrow \end{array},$$

$$(4) \quad \begin{array}{c} \circlearrowright \end{array} = \begin{array}{c} \circ \end{array},$$

$$(5) \quad \begin{array}{c} \uparrow \\ \leftarrow \ell \end{array} = q^{\mp} \begin{array}{c} \uparrow \\ \leftarrow \ell \end{array},$$

where the sign \mp in the last relation is the opposite the sign \pm of the component of ℓ involved.

Remark 2.2. The dependence of $\text{Sk}_q^{\text{GL}_1}(Y, \ell)$ on the framing line ℓ is only through its homology class $[\ell] \in H_1(Y)$, in that any 2-chain η with boundary $\partial\eta = \ell - \ell'$ induces a natural

isomorphism $\text{Sk}_q^{\text{GL}_1}(Y, \ell) \cong \text{Sk}_q^{\text{GL}_1}(Y, \ell')$; it sends each framed, oriented link $[L] \in \text{Sk}_q^{\text{GL}_1}(Y, \ell)$ to $q^{L \cdot \eta}[L] \in \text{Sk}_q^{\text{GL}_1}(Y, \ell')$.

Remark 2.3. It is often convenient to allow half-twists (i.e., half-integer framings) on the links generating the skein module. This can be done simply by extending the base ring to $\mathbb{Z}[q^{\pm \frac{1}{2}}]$ and introduce the following extra relation:

$$(6) \quad \begin{array}{c} \text{---} \\ \diagup \quad \diagdown \\ \text{---} \end{array} = q^{\frac{1}{2}} \begin{array}{c} \text{---} \\ | \\ \text{---} \end{array} .$$

Definition 2.4. If, in addition, Y is equipped with a closed 1-form ζ , there is an *action filtration* $\{\text{Sk}_q^{\text{GL}_1}(Y, \ell)_{\leq E}\}_{E \in \mathbb{R}}$ on the skein module, where $\text{Sk}_q^{\text{GL}_1}(Y, \ell)_{\leq E}$ is the submodule of $\text{Sk}_q^{\text{GL}_1}(Y, \ell)$ spanned by links κ for which $\int_{[\kappa]} \zeta \leq E$. Define the *action completion* $\widehat{\text{Sk}}_q^{\text{GL}_1}(Y, \ell)$ to be the colimit with respect to this filtration:

$$\widehat{\text{Sk}}_q^{\text{GL}_1}(Y, \ell) = \text{colim}_{E \rightarrow \infty} \text{Sk}_q^{\text{GL}_1}(Y, \ell)_{\leq E}.$$

2.4. Skein-valued flow loop count.

Definition 2.5. In the setting as in Sections 2.1-2.2 above, define the GL_1 -skein-valued flow loop count to be

$$\Phi_{S^3 \setminus K} := \sum_{\gamma \in \mathcal{O}} (-1)^{e(\gamma) + \text{nh}(\gamma)} [\gamma] \in \widehat{\text{Sk}}_q^{\text{GL}_1}(S^3 \setminus K, \ell_{\text{fr}}),$$

where $[\gamma]$ denotes the class of the corresponding framed, oriented link in the skein module $\text{Sk}_q^{\text{GL}_1}(S^3 \setminus K, \ell_{\text{fr}})$.

While much of the discussion in this section generalizes straightforwardly to any fibered 3-manifold, what is particularly nice about fibered knot complements is that we can canonically identify the skein module with the ring of two-variable series:

Proposition 2.6. *There is a canonical isomorphism*

$$\widehat{\text{Sk}}_q^{\text{GL}_1}(S^3 \setminus K, \ell_{\text{fr}}) \cong \mathbb{Z}[q^{\pm 1}]((x)),$$

which sends the positive meridian of K to x .

Proof. Using the GL_1 -skein relations given in Definition 2.1, it is easy to see that any framed oriented link L can be turned into some parallel copies of the 0-framed meridian times a power of q . Moreover, the power of q is uniquely determined; it is given by the linking number

$$\text{lk}(L, L) - \text{lk}(L, \ell_{\text{fr}}),$$

where $\text{lk}(L, \ell_{\text{fr}}) = \text{lk}(L, \ell_{\text{fr}}^+) - \text{lk}(L, \ell_{\text{fr}}^-)$ if ℓ_{fr}^{\pm} denotes the \pm -signed components of ℓ_{fr} . This proves the isomorphism. \square

With this isomorphism, we can turn the GL_1 -skein-valued flow loop count defined in Definition 2.5 into an explicit two-variable series

$$\Phi_{S^3 \setminus K}(x, q) \in \mathbb{Z}[q^{\pm 1}][[x]].$$

This is the form used in the statement of Theorem A.

Remark 2.7. As described briefly in the introduction, the count in Definition 2.5 is (the GL_1 -reduction of) the skein-valued curve count in $(T^*S^3, S^3 \sqcup M_K)$, where M_K denotes the knot complement Lagrangian, obtained from a Lagrangian surgery on the clean intersection between the conormal Lagrangian L_K and the zero section S^3 , shifted off the zero section along a non-vanishing closed 1-form; see [CEL26]. Alternatively, we can view $S^3 \setminus K$ as a 3-manifold with cylindrical end, and count holomorphic curves in $(T^*(S^3 \setminus K), S^3 \setminus K \sqcup S^3 \setminus K)$, where the Lagrangians $S^3 \setminus K$ are shifted off from each other using a non-vanishing closed 1-form.⁷

The framing vector field ξ_{fr} determines a 4-chain that can be used in this count. When the shift is small, the correspondence between holomorphic curves and Morse flow graphs [Ekh07] (see also [ELPS25, Appendix A]) shows that all the holomorphic curves are holomorphic annuli (and their multiple covers), which correspond to Morse flow loops, and this is what we are counting.

Proof of Theorem A. We need to show that $\Phi_{S^3 \setminus K}(x, q)$ is independent of all the choices we have made: the circle-valued Morse function, the metric, and the framing vector field. Note that any choice can be smoothly deformed to another along a generic 1-parameter family. The desired invariance follows immediately from the corresponding deformation invariance of skein-valued curve count [ES26] and Remark 2.7.

For an alternative, elementary proof of invariance via bifurcation analysis, see Appendix A. □

2.5. Adding extra Wilson line defects. Before we conclude this section, we remark that Theorem A is a special case of a more general theorem, where we allow insertion of extra Wilson line defects in $S^3 \setminus K$:

Theorem 2.8. *For any fibered knot K , we have the “abelianization” homomorphism⁸*

$$\text{Ab} : \text{Sk}_q^{\text{GL}_2}(S^3 \setminus K) \rightarrow \text{Sk}_q^{\text{GL}_1}(S^3 \setminus K)^{\otimes 2}.$$

Proof. This is a special case of the skein trace map [ELPS25, Theorem 1.3], applied to the trivial double cover Lagrangian $S^3 \setminus K \sqcup S^3 \setminus K \subset T^*(S^3 \setminus K)$. □

The skein-valued flow loop count in Definition 2.5 is nothing but the image of the empty skein under this abelianization map:

$$\Phi_{S^3 \setminus K}(x, q^2) = \text{Ab}([\emptyset]).$$

The following conjecture generalizes Conjecture 1.3:

Conjecture 2.9. *The abelianization map in Theorem 2.8 is equivalent to the one constructed using quantum groups [Par26, Theorem B].⁹*

⁷To be more precise, the skein-valued curve count would give $\Phi_{S^3 \setminus K}(x, q^2)$, since all the linking numbers are counted twice, from the two copies of the GL_1 -skein module.

⁸As before, the GL_1 -skein module on the right-hand side is twisted by framing lines and action-completed; we just omitted it for simplicity of notation.

⁹We used SL_2 -skein modules in [Par26], but they can be turned into GL_2 -skein modules by multiplying each framed, oriented link L by $q^{\frac{\sum_i \text{lk}(L_i, L_i)}{4}}$, where the sum is over all connected components L_i of L .

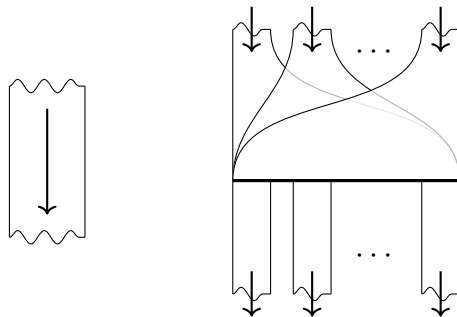


FIGURE 2. Left: a strip supporting a flow along the direction of the arrow. Right: ends of strips glued along a branch line.

3. GEOMETRIC STATE SUM MODELS ON KNOT HOLDERS

In this section, we explain how one can compute the flow loop count defined in Section 2 in practice. The key idea is to reduce the dynamics of Morse flow into the symbolic dynamics on the corresponding knot holder, which in turn gives rise to a state sum model on knot holders.

3.1. Knot holders. We first review the theory of knot holders. See [BW83a] for the original paper and [GHS97] for a comprehensive review.

Definition 3.1 ([GHS97, Definition 2.2.1]). A *template* is a branched surface with boundary, supporting an expansive semiflow.

Here, “semiflow” means that the flow is only defined in forward time direction, and “expansive” means that the volume is expanding everywhere. In other words, a template is a union of strips, whose ends are glued along some branch lines where they can first join and then split; see Figure 2.

A template embedded in a 3-manifold is called an *embedded template*, or a *knot holder* [BW83a], as it can “hold knots”; any closed 1-manifold drawn on a knot holder along the direction of the semiflow determines a framed¹⁰, oriented link in the ambient 3-manifold.

A template \mathcal{T} determines a symbolic dynamical system known as a *shift of finite type* (SFT¹¹) $\Sigma_{\mathcal{T}}$ as follows. Assign a symbol to each strip. Given any symbol, look at the branch line corresponding to the outgoing end of the strip corresponding to that symbol. The strips whose incoming ends are glued to that branch line determine the symbols that can follow the given symbol. Then, $\Sigma_{\mathcal{T}}$ is defined to be the set of all forward orbits, i.e., sequences

$$\mathbf{a} = a_0 a_1 a_2 \cdots$$

of symbols obeying the admissibility condition (i.e., outgoing end of the strip a_n is glued to the incoming end of the strip a_{n+1}). The shift map

$$\begin{aligned} \sigma : \Sigma_{\mathcal{T}} &\rightarrow \Sigma_{\mathcal{T}} \\ a_0 a_1 a_2 \cdots &\mapsto a_1 a_2 a_3 \cdots \end{aligned}$$

¹⁰The framing is induced by the normal direction to the knot holder; since the knot holder may be unorientable, here we are allowing half-twists in the framing.

¹¹Not to be confused with Symplectic Field Theory [EGH00], which is also very much relevant to skein-valued curve counts; see [ELPS25, Sec. 8.3].

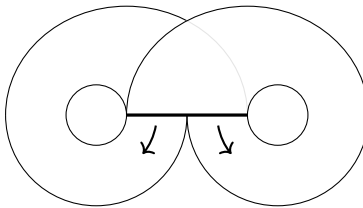


FIGURE 3. Lorenz knot holder

describes the discrete time evolution in this symbolic dynamical system. In this language, a knot contained in a knot holder corresponds to a periodic sequence of the symbols.

Knot holders are central to the study of dynamics of three-dimensional flows, thanks to the following powerful theorem of Birman and Williams:

Theorem 3.2 ([BW83a, Theorem 2.1]). *Given a flow ϕ_t on a 3-manifold M having a hyperbolic chain-recurrent set, there is a knot holder \mathcal{H} in M such that the link of periodic orbits L_ϕ of the flow is in one-to-one correspondence (via isotopy) with the link of periodic orbits $L_{\mathcal{H}}$ on the knot holder.¹²*

See, e.g., [GHS97, Sec. 1.2], for a concise introduction to basic notions in dynamical systems, including the definition of the chain-recurrent set and its hyperbolicity. Here, we just remark that it is a mild assumption that can always be achieved in the cases of our interest, by modifying the circle-valued Morse function appropriately. Hence, the dynamics of a three-dimensional flow can be encoded in the symbolic dynamics on a knot holder, at least when it comes to questions on periodic orbits and their link types.

Example 3.3. The Lorenz knot holder [BW83b], which is a knot holder for the Lorenz system (Figure 1), is shown in Figure 3.

3.2. Knot holders for fibered link complements. Here, we describe in detail how to construct a knot holder for the suspension flow in any mapping torus of a surface with boundary, such as in any fibered link complement.

Definition 3.4. Given a compact, connected, oriented surface F , a *marking* on F consists of the following:

- (1) A collection of (green) non-intersecting arcs $\alpha_1, \dots, \alpha_n \subset F$ with boundary points on ∂F , such that $F \setminus (\alpha_1 \cup \dots \cup \alpha_n)$ is a disjoint union of disks.
- (2) A collection of (red) base points $p_1, \dots, p_m \in \text{int}(F \setminus (\alpha_1 \cup \dots \cup \alpha_n))$, one for each disk component.

If F is a surface of genus g and b boundary components, then $n \geq 2g + (b - 1)$, and

$$m = \chi(F \setminus (\alpha_1 \cup \dots \cup \alpha_n)) = 2 - 2g - b + n.$$

See Figure 4 for an example of a marked surface, where the arcs are drawn in green, and the base points are drawn in red.

Remark 3.5. Note that, given such a marking, there is a Morse function on F for which

- (1) the boundary ∂F is a level set which is the global minimum,

¹²To be precise, with at most two extra orbits in $L_{\mathcal{H}}$, coming from the DA (“derived from Anosov”) procedure, when the dimension of the chain-recurrent set is > 1 .

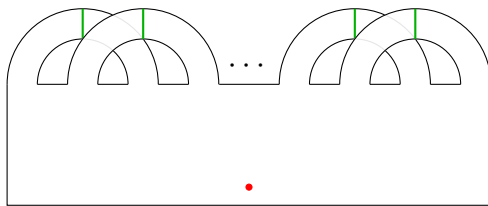


FIGURE 4. A marked surface

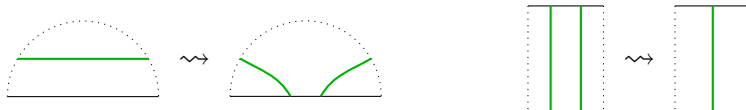


FIGURE 5. Splitting (left) and joining (right)

- (2) the (red) base points are the local maxima, and
- (3) the (green) arcs are the descending manifolds of the saddle points.

Given a marking on F , any self-diffeomorphism $\varphi : F \rightarrow F$ fixing the boundary ∂F pointwise, induces another marking on F ; we will simply denote the resulting marked surface by $\varphi(F)$. By choosing some isotopy of φ , we may assume that φ preserves the set of base points, $\{p_1, \dots, p_m\} = \{\varphi(p_1), \dots, \varphi(p_m)\}$.¹³ Since each disk component D of $F \setminus (\alpha_1 \cup \dots \cup \alpha_n)$ contains a base point in the interior, we can isotope all parts of the arcs of $\varphi(F)$ drawn on D to a small neighborhood of the boundary ∂D , without crossing the base point. We can then split the arcs by colliding them with the boundary $\partial D \cap \partial F$ (i.e., the part of ∂D which is not in $\alpha_1 \cup \dots \cup \alpha_n$) using the move shown in the left of Figure 5. After such splitting, we will have a collection of arcs each of which is parallel to some arc α_i . We then join the parallel arcs using the move shown in the right of Figure 5.

The movie of splitting and joining of arcs we just described determines a branched surface $S \subset F \times [0, 1]$ such that

- (1) $S \cap (F \times \{0\}) = \varphi(\alpha_1 \cup \dots \cup \alpha_n)$,
- (2) $S \cap (F \times \{1\}) = \alpha_1 \cup \dots \cup \alpha_n$, and
- (3) S is disjoint from $\{p_1, \dots, p_m\} \times [0, 1] \subset F \times [0, 1]$.

Gluing the two boundary components of $F \times [0, 1]$ by the monodromy φ (i.e., $(q, 1) \sim (\varphi(q), 0)$ for any $q \in F$), we obtain the mapping torus M_φ of φ , equipped with

- (1) a branched surface $\mathcal{H} := S / \sim \subset M_\varphi$, and
- (2) an oriented link $\gamma_e := (\{p_1, \dots, p_m\} \times [0, 1]) / \sim \subset M_\varphi$ disjoint from \mathcal{H} .

By deforming the suspension flow of on M_φ using the movie of Morse functions on F corresponding to the movie of markings, we obtain a Morse flow on the mapping torus M_φ such that

- (1) each component of γ_e is an elliptic flow loop which is a source (i.e., a repeller), and
- (2) \mathcal{H} is the knot holder for the flow, supporting all the hyperbolic flow loops.

We summarize this construction as a corollary of Theorem 3.2:

¹³ φ may permute the base points.

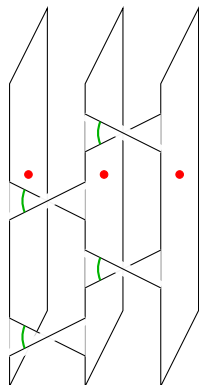


FIGURE 6. A natural choice of marking on a braided Seifert surface; the red base points are the intersection of the braid axis with the braided Seifert surface, and the green arcs are the cocores of the bands.

Corollary 3.6. *For any mapping torus M_φ of a surface F with boundary, one can choose some metric and a circle-valued Morse function on M_φ in such a way that*

- (1) *the boundary of M_φ is a sink of the Morse flow,*
- (2) *all the periodic orbits of the Morse flow are nondegenerate,*
- (3) *the hyperbolic flow loops are in one-to-one correspondence with periodic orbits of the symbolic dynamics on the knot holder \mathcal{H} , and*
- (4) *the (primitive) elliptic flow loops are in one-to-one correspondence with the components of the link γ_e .*

Moreover, the one-to-one correspondence of the periodic orbits is by ambient isotopy.

We now specialize the construction described above to the case of fibered link complements. Let $K \subset S^3$ be a fibered link, and let F be its minimal genus Seifert surface, which is unique up to isotopy. We can then view the complement $S^3 \setminus K$ as the mapping torus M_φ of the monodromy map $\varphi : F \rightarrow F$. In this setup, there are two convenient choices for the repelling elliptic flow loops γ_e (i.e., the movie of red base points):

- Meridian of $K \subset S^3$: in this case, there will be a single red base point $p \in F$ close to the boundary. This choice of elliptic flow loop contributes an overall factor of $1 - x$ to $\Phi_{S^3 \setminus K}$, as it has 0 linking number with any other hyperbolic flow loops in \mathcal{H} .
- Braid axis of $F \subset S^3$ as a braided Seifert surface [Rud83]: in this case, the number of red base points on F is equal to the number of braid strands. While we would no longer have a nice factorization of the contribution of elliptic flow loops (as they link non-trivially with hyperbolic flow loops), this choice is often useful if we want the knot holder to be adapted to a knot diagram, as we can then choose the arcs $\alpha_1, \dots, \alpha_n$ to sit at the bands of the braided Seifert surface; see Figure 6.

Example 3.7 (Trefoil knot complement). We illustrate the construction of knot holders though the simplest non-trivial fibered knot, namely the trefoil knot $K = \mathbf{3}_1^+$. Start with the minimal genus Seifert surface F of K , which is illustrated in the left of Figure 7. Let us choose a marking with two arcs and a base point close to the boundary, as shown in the figure, so that γ_e is a small meridian of K . The monodromy $\varphi : F \rightarrow F$ can be determined by pulling the arcs—considered as elastic cords in $S^3 \setminus F$ with fixed boundary points—from

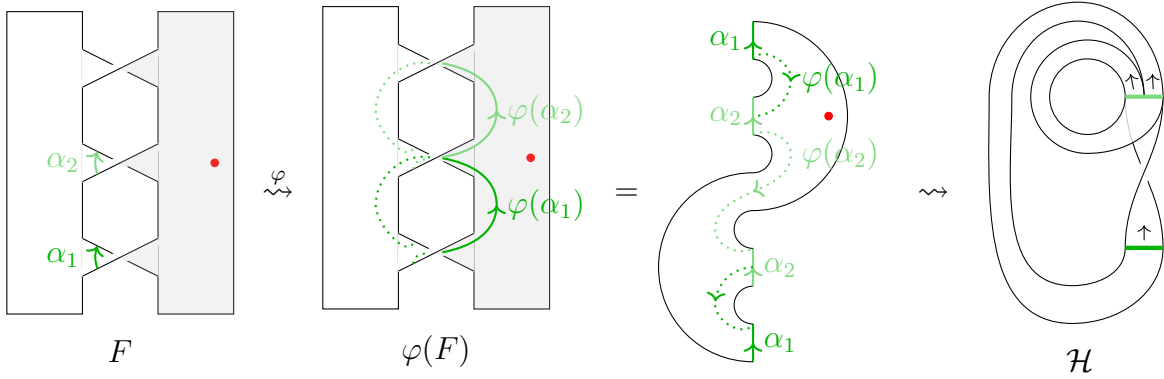


FIGURE 7. Left: the minimal genus Seifert surface of the trefoil knot with a marking. Middle: monodromy action on the marking. Right: resulting knot holder.

the front side of F to the back side of F [BG16]. Middle of Figure 7 shows the new marking after this monodromy action, where we also show how this new marking looks in the disk $F \setminus (\alpha_1 \cup \alpha_2)$. Pushing the new marking to the boundary of this disk, we see that $\varphi(\alpha_1)$ becomes α_2 with the opposite orientation, and that $\varphi(\alpha_2)$ splits into α_1 and α_2 . In particular, the monodromy action on $H_1(F, \partial F)$ is given by

$$\varphi \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \alpha_1 \\ \alpha_2 \end{pmatrix}.$$

But the picture tells us much more than just the action on homology; by tracing exactly how the arcs split and join, we obtain the corresponding knot holder \mathcal{H} in $S^3 \setminus K$, shown on the right of Figure 7. The resulting knot holder turns out to look like the Lorenz knot holder (Figure 3) but with a half-twist, also known as the Smale horseshoe knot holder. The green lines shown on \mathcal{H} are the arcs $\mathcal{H} \cap F = \alpha_1 \cup \alpha_2$; given any flow loop supported on \mathcal{H} , its linking number with K can be computed simply by looking at how many times it crosses those green lines.

Example 3.8 (Complement of braid-homogeneous links). Here, we explain how to read off a knot holder directly from any closure of a homogeneous braid. This will be a crucial ingredient in the proof of Theorem B in Section 5.

Recall that a braid word $\beta = \sigma_{i_1}^{\epsilon_1} \sigma_{i_2}^{\epsilon_2} \cdots \sigma_{i_k}^{\epsilon_k}$, $\epsilon_j = \pm 1$, in the standard Artin generators $\sigma_1, \dots, \sigma_{N-1}$ is called *homogeneous* if

- (1) every σ_i occurs at least once, and
- (2) for each i , the exponents of all occurrences of σ_i are the same.

Stallings [Sta78] showed that any braid-homogeneous link (i.e., any closure of homogeneous braid) is fibered, with the fiber surface F given by N copies of disks, one for each braid strand, connected by bands attached according to the braid word; Figure 6 shows such a fiber surface in case $\beta = \sigma_1 \sigma_2^{-1} \sigma_1 \sigma_2^{-1}$. That this is a fiber surface immediately follows from the fact that it is the Murasugi sum of fiber surfaces of $(2, n_i)$ -torus links, $1 \leq i \leq N - 1$, where n_i is the number of occurrences of σ_i in β , counted with sign.

On such a fiber surface F , we choose a marking as in Figure 6. That is, we declare that the braid axis is a repelling elliptic flow loop γ_e (of period N), and draw arcs on F , one for

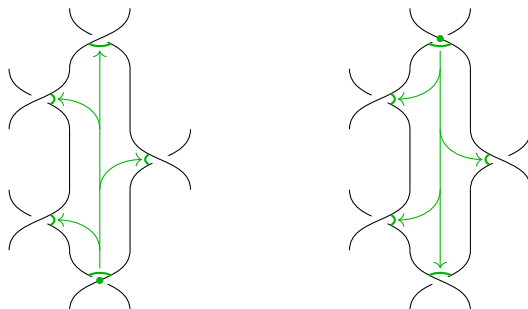


FIGURE 8. Pulling and splitting elastic cords

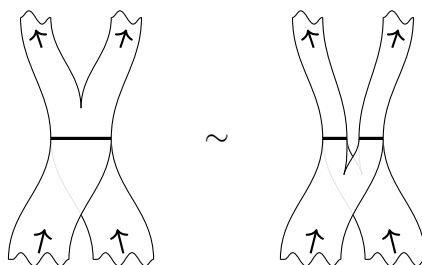


FIGURE 9. Equivalent knot holders; they have the same periodic orbits.

each band. In this setup, to determine the monodromy map $\varphi : F \rightarrow F$, we consider elastic cords in $S^3 \setminus F$ with boundary on ∂F , given by the positive push-offs of the arcs to the front side of F ; for positive crossings, the elastic cord would be above the band, while for negative crossings, the elastic cord would be below the band. There is a natural way to pull each of these elastic cords, without crossing the braid axis γ_e , to split it into a number of other arcs. Given an elastic cord at a crossing, we look at the region of the plane delimited by the homogeneous braid closure diagram that is directly above (resp., below) the crossing if it is a positive (resp., negative) crossing; see Figure 8. The region is a polygon whose vertices correspond to some crossings. We can then pull the elastic cord across this polygon, splitting it into a number of elastic cords corresponding to the other vertices of the polygon, as shown in Figure 8. Note that, the new elastic cords are at the back side of F , except for the ones which move to the right column, which are still at the front side of F . For the ones which move to the right column, we can repeat this process, and this process eventually terminates, as there are only $N - 1$ columns in the braid. In this way, we can pull each of the elastic cords from the front side of F to the back side of F , showing directly that F is a fiber surface, according to the fiberedness criterion of [BG16].¹⁴ What is more, since we have an explicit description of how the elastic cords are dragged around, by drawing the locus the elastic cords sweep around, we obtain a knot holder \mathcal{H} for the braid-homogeneous link that can be directly read off from the homogeneous braid; see Figure 10. The arcs $\mathcal{H} \cap F$ (shown in green in the right of Figure 10) correspond to the crossings of the braid β , and the way the strips split and join directly models the way the elastic cords do.

¹⁴For the purpose of getting a knot holder, we wouldn't need to repeat the process though, as they will lead to equivalent knot holders, under the second move in [BW83a, Fig. 2.4], which is reproduced in Figure 9.

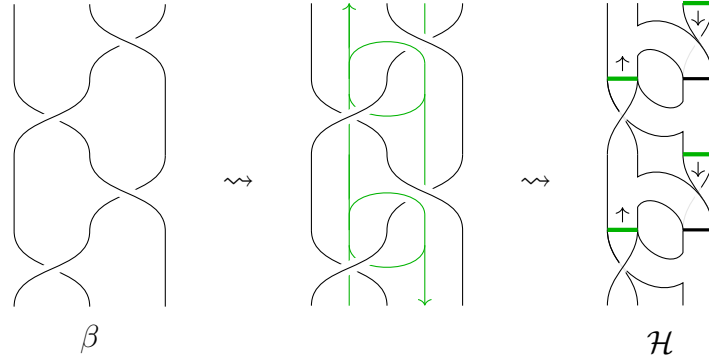


FIGURE 10. Reading off a knot holder from a homogeneous braid. Left: a homogeneous braid. Middle: how the elastic cords move around. Right: the resulting knot holder.

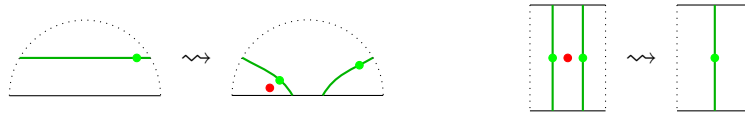


FIGURE 11. Splitting (left) and joining (right), with framing lines (red: elliptic, green: hyperbolic)

3.3. Framing adapted to knot holders. Now that we have seen how to obtain knot holders in practice, we would like to discuss how to compute the GL_1 -skein-valued flow loop count (Definition 2.5) from the knot holders. As in Corollary 3.6, let $\mathcal{H} \subset S^3 \setminus K$ be a knot holder supporting all the hyperbolic flow loops, and $\gamma_e \subset (S^3 \setminus K) \setminus \mathcal{H}$ be the oriented link of elliptic flow loops. In order to count these flow loops in the GL_1 -skein module, we need to choose a framing, as in Section 2.2. For the purpose of obtaining a simple state sum model, we would in particular want the framing induced on flow loops to be the same as the one from the tangent direction of the knot holder.¹⁵

Such a framing can be constructed as follows. On a marked fiber surface F , we set the perturbation vector field ξ_{pert} to be the one coming from a Morse function associated to the marking on the surface, as in Remark 3.5. That is, we pick an interior point q_i from each arc α_i in the marking of F , and choose a Morse function on F for which red base points p_1, \dots, p_m are the local maxima, the chosen interior points q_1, \dots, q_n are the saddle points, and the arc α_i is the descending manifold from the saddle q_i . Then, in the mapping cylinder $F \times [0, 1]$ of a monodromy $\varphi : F \rightarrow F$, $\{p_1, \dots, p_m\} \times [0, 1]$ are the elliptic framing lines, and $\{q_1, \dots, q_n\} \times [0, 1]$ are the hyperbolic framing lines.

It remains to describe how to close up the mapping cylinder; how the framing lines behave under splitting and joining of the arcs. This is depicted in Figure 11.

- As an arc split into two, a pair of a saddle point and a local maximum gets created, near the splitting point; see the left of Figure 11. Up to isotopy, the movie of critical

¹⁵The knot holder may not be orientable, so here we are allowing half-twists; see Remark 2.3. By shifting the framing lines off the knot holder, we can obtain genuine framings without half-twists, but that's less convenient, as it would be different from the one induced by the knot holder.

points under splitting is uniquely determined as follows. After splitting, F minus the arcs acquires an extra disk component which does not already contain a local maximum. A new local maximum is created in the interior of that disk component, and a new saddle point is created in the arc component neighboring that disk. The original saddle point on the arc follows along the other component of the arc after splitting.

- As two arcs join, two saddle points sandwich a local maximum and combine into a single saddle; see the right of Figure 11.

The movie of these saddle points and local maxima determine the framing line

$$\ell_{\text{fr}} = \gamma_e \cup \gamma_h \cup \ell_{\text{pair}},$$

where γ_e is the movie of the local maxima $\{p_1, \dots, p_m\}$ (which coincide with the elliptic flow loops), γ_h is the movie of saddle points $\{q_1, \dots, q_n\}$, and ℓ_{pair} is the movie of pairs of saddle points and local maxima that get created and annihilated under splitting and joining. Note, all the hyperbolic framing lines are on the knot holder, while all the elliptic framing lines are off the knot holder.

Now that we have a perturbation vector field ξ_{pert} which is, away from the framing lines, everywhere tangent to the knot holder \mathcal{H} , the framings induced on flow loops are the same as the ones induced by the knot holder. We can thus identify the d -fold multiple cover of any primitive hyperbolic flow loop $\gamma \subset \mathcal{H}$ with d parallel copies of γ (parallel in the knot holder), in the GL_1 -skein module. This allows us to reformulate the GL_1 -skein-valued flow loop count in terms of a simple state sum model on the knot holder, which we describe below.

3.4. State sum on knot holders. Let \mathcal{H} be a knot holder, $\gamma_e \subset (S^3 \setminus K) \setminus \mathcal{H}$ the elliptic flow loops, and ℓ_{fr} the framing lines as above. Then, by a *state*, we mean an assignment of 0 or 1 to each component of γ_e , together with an assignment of a nonnegative integer on each strip of the knot holder \mathcal{H} , satisfying the admissibility condition that the sum of the numbers assigned to the incoming strips is equal to the sum of the numbers assigned to the outgoing strips, for any splitting or joining chart. Let $\mathcal{S}(\mathcal{H}, \gamma_e)$ denote the set of all such states.

Any multi-flow loop $\gamma \in \mathcal{O}$ (in the sense of Section 2.1) determines a state $\sigma(\gamma) \in \mathcal{S}(\mathcal{H}, \gamma_e)$, by counting the number of times γ passes through each strip of the knot holder, and by recording which components of γ_e are contained in γ . On the other hand, for any given state $\sigma \in \mathcal{S}(\mathcal{H}, \gamma_e)$, there are only finitely many multi-flow loops $\gamma \in \mathcal{O}$ for which $\sigma(\gamma) = \sigma$. Such multi-flow loops can be easily determined. For each strip of the knot holder, if the assigned integer is $a \in \mathbb{Z}_{\geq 0}$, then we simply draw a parallel strands on that strip, along the direction of the semiflow of the knot holder. These parallel strands can be uniquely connected across the splitting charts. The only non-trivial things can happen near the joining charts. If there are b and c incoming strands and $a = b + c$ outgoing strands in a joining chart, then there are $\binom{b+c}{b}$ number of ways to connect these strands across the joining chart. Once we have connected all the strands across all the joining charts, we get a multi-flow loop $\gamma \in \mathcal{O}$, and these are all the multi-flow loops with a given state.

We can now repackage the flow loop count, which was defined in Definition 2.5 as a sum over all multi-flow loops $\gamma \in \mathcal{O}$, into a sum over all states:

$$\Phi_{S^3 \setminus K}(x, q) = \sum_{\sigma \in \mathcal{S}(\mathcal{H}, \gamma_e)} w(\sigma).$$

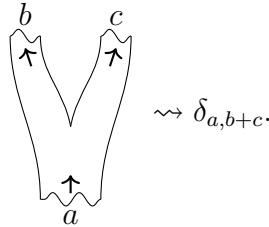
Here, the weight $w(\sigma)$ is simply the sum of weights of all the multi-flow loops γ for which $\sigma(\gamma) = \sigma$:

$$w(\sigma) = \sum_{\substack{\gamma \in \mathcal{O} \\ \sigma(\gamma) = \sigma}} (-1)^{e(\gamma) + \text{nh}(\gamma)} q^{\text{lk}(\gamma, \gamma) - \text{lk}(\gamma, \ell_{\text{tr}})} x^{\text{deg } \gamma}.$$

What makes this state sum particularly nice is that, all the terms in the weight $w(\sigma)$ except for the self-linking number $\text{lk}(\gamma, \gamma)$ depend only on the state σ , not on a particular multi-flow loop γ representing it. Moreover, the sum $\sum_{\sigma(\gamma) = \sigma} q^{\text{lk}(\gamma, \gamma)}$ is given by a product of q -binomials.

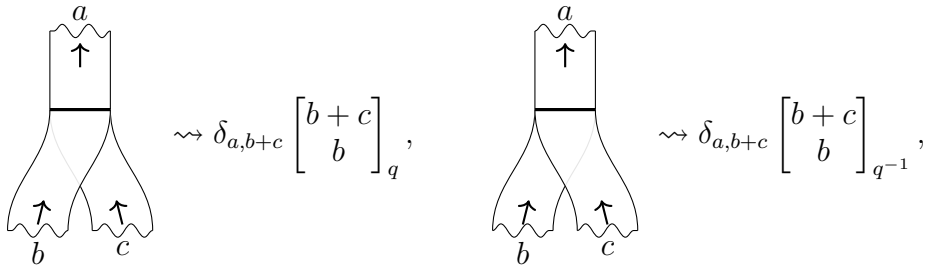
More explicitly, the weight $w(\sigma)$ is determined by the product of following local factors:

- Splitting:



That is, no extra factor from splitting charts, other than imposing the admissibility condition.

- Joining:

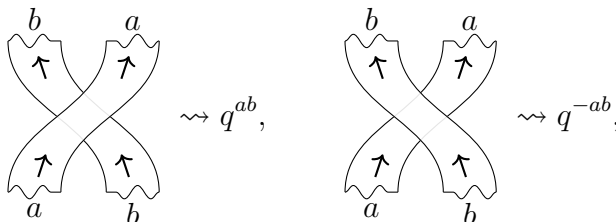


where the q -binomial coefficients are defined by

$$\begin{bmatrix} n \\ k \end{bmatrix}_q := \frac{[n]_q!}{[k]_q! [n-k]_q!}, \quad [n]_q! := [n]_q [n-1]_q \cdots [1]_q, \quad [n]_q := \frac{1 - q^n}{1 - q}.$$

Such q -binomial factors arise from summing $q^{\text{lk}(\gamma, \gamma)}$ over all possible ways to connect the strands across the joining charts. Note that we are using a particular planar diagram of the knot holder to determine whether the crossings are positive or negative under joining.

- Crossings and half-twists:



$$\begin{array}{c} a \\ \uparrow \\ \text{---} \\ \uparrow \\ a \end{array} \rightsquigarrow (-1)^a q^{\frac{a}{2}}, \quad \begin{array}{c} a \\ \uparrow \\ \text{---} \\ \uparrow \\ a \end{array} \rightsquigarrow (-1)^a q^{-\frac{a}{2}}.$$

The powers of q come from the self-linking numbers of γ , and the signs $(-1)^a$ in the half-twists come from the fact that negative hyperbolic flow loops are counted with signs (i.e., $(-1)^{\text{nh}(\sigma)}$).

- Elliptic flow loops: Of course, the factors described above only account for the linking numbers among hyperbolic flow loops, so there is also a monomial factor coming from the linking numbers with the elliptic flow loops specified by σ , together with the sign $(-1)^{e(\sigma)}$.
- Degree: The factor $x^{\text{deg } \sigma}$ can be easily determined, as $\text{deg } \sigma$ is simply the sum of the numbers on the strips corresponding to the arcs $\mathcal{H} \cap F$, plus the sum of the degrees of the elliptic flow loops used in σ .
- Linking with the framing lines: Now it remains to describe how to determine the framing factor $q^{-\text{lk}(\sigma, \ell_{\text{fr}})}$. Recall that $\ell_{\text{fr}} = \gamma_e \cup \gamma_h \cup \ell_{\text{pair}}$, where ℓ_{pair} is the locus of pairs of saddles and local maxima that get created under splitting and annihilated under joining. Whenever such a pair is created, it is created near one of the inner boundaries of the splitting chart, so we use the convention to keep them near one of the two boundaries of the strips, though we allow them to slide from one boundary to the other occasionally. Whenever it slides, we pick up a linking factor, from the linking number with the elliptic component of the pair:

$$\begin{array}{c} a \\ \uparrow \\ \text{---} \\ \uparrow \\ a \end{array} \rightsquigarrow q^{-\frac{a}{2}}, \quad \begin{array}{c} a \\ \uparrow \\ \text{---} \\ \uparrow \\ a \end{array} \rightsquigarrow q^{\frac{a}{2}},$$

where on the left (resp., right) the elliptic component of the pair, shown in red, is above (resp., below) the strip. Whenever the pair gets annihilated at a joining, by sliding it to the other side if necessary, we make sure that the pair starts from the boundary of the strip that is closer to the other strip (in the planar diagram) that gets joined together. This is to ensure that there is no extra framing factor coming from such joining. For instance,

$$\rightsquigarrow \delta_{a,b+c} \left[\begin{array}{c} b+c \\ b \end{array} \right]_q,$$

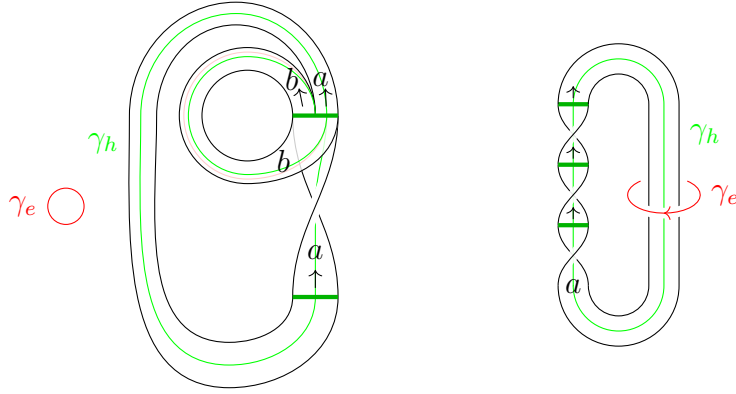


FIGURE 12. State sums on two knot holders for the trefoil knot

since there is no extra framing factor in this picture. If the pair was starting from the other boundary of the strip labeled b , then there would be an extra factor of $q^{\frac{b}{2}}$ coming from sliding the pair from left to right. Finally, the linking numbers with γ_e and γ_h can be easily determined.

Below, we illustrate our state sum model on knot holders through examples.

Example 3.9 (State sum on trefoil knot holders). Let us consider state sums on two trefoil knot holders, one from Example 3.7, and the other from Example 3.8, as shown in Figure 12. The state sum on the knot holder on the left of Figure 12 results in the following formula for the flow loop count:

$$\begin{aligned} \Phi_{S^3 \setminus \mathfrak{z}_1^r}(x, q) &= (1-x) \sum_{a,b \geq 0} (-1)^a q^{\frac{a^2}{2}} \begin{bmatrix} a+b \\ a \end{bmatrix}_q x^{a+(a+b)} \cdot q^{\frac{a}{2}} \\ &= 1 - qx^2 - q^2x^3 + q^5x^5 + q^7x^6 - q^{12}x^8 - q^{15}x^9 + O(x^{11}), \end{aligned}$$

where the overall factor of $(1-x)$ comes from the elliptic flow loop along the meridian, and the factor $q^{\frac{a}{2}}$ comes from the linking with the framing line γ_h .

The state sum on the knot holder on the right of Figure 12 gives:

$$\begin{aligned} \Phi_{S^3 \setminus \mathfrak{z}_1^r}(x, q) &= \sum_{\substack{a \geq 0 \\ 0 \leq \epsilon \leq 1}} (-1)^a q^{\frac{3a^2}{2} + 2\epsilon a} x^{3a} (-x^2)^\epsilon \cdot q^{\frac{3a}{2} + \epsilon - a} \\ &= 1 - qx^2 - q^2x^3 + q^5x^5 + q^7x^6 - q^{12}x^8 - q^{15}x^9 + O(x^{11}), \end{aligned}$$

where ϵ counts the elliptic flow loop γ_e , and the factor $q^{\frac{3a}{2} + \epsilon}$ (resp., q^{-a}) comes from the linking with the framing line γ_h (resp., γ_e).

Observe that they give the same count, which follows from Theorem A. Moreover, they agree with the BPS q -series for the trefoil knot complement [GM21, Par20]

$$-q^{-1}x^{-\frac{1}{2}} \widehat{Z}_{S^3 \setminus \mathfrak{z}_1^r}(x, q) = 1 - qx^2 - q^2x^3 + q^5x^5 + q^7x^6 - q^{12}x^8 - q^{15}x^9 + O(x^{11}),$$

which is a special case of Theorem B.

Example 3.10 (State sum on figure-eight knot holders). Let us consider state sums on two figure-eight knot holders, one from the “direct model” of [BW83a] (which can be derived in

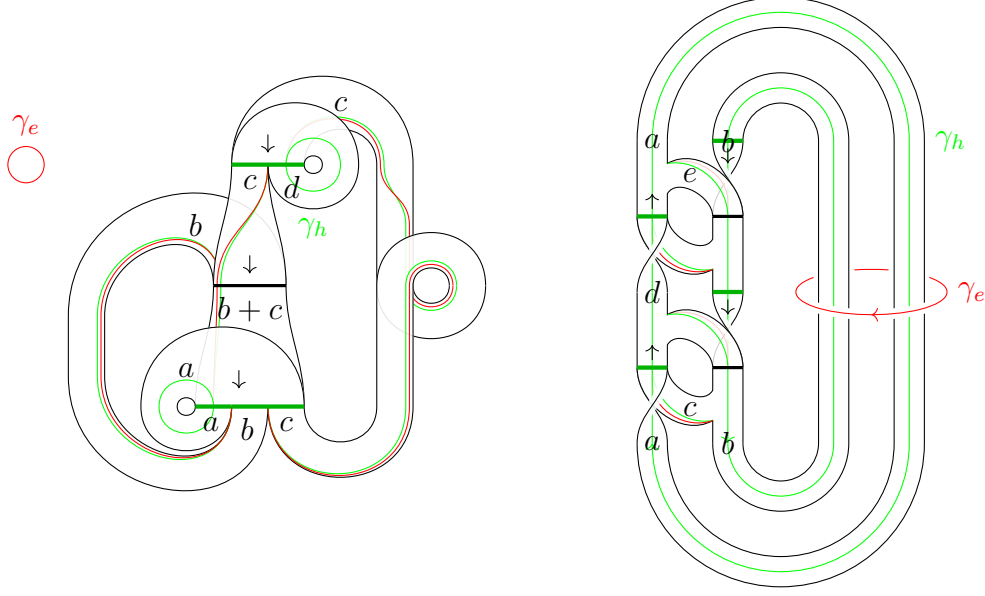


FIGURE 13. State sums on two knot holders for the figure-eight knot

the same manner as in Example 3.7), and the other¹⁶ from Example 3.8, as shown in Figure 13. From the first knot holder on the left of Figure 13, we have:

$$\begin{aligned} \Phi_{S^3 \setminus \mathcal{A}_1}(x, q) &= (1-x) \sum_{a,b,c,d \geq 0} q^{c^2} \begin{bmatrix} a+b+c \\ a \end{bmatrix}_{q^{-1}} \begin{bmatrix} b+c \\ b \end{bmatrix}_q \begin{bmatrix} c+d \\ c \end{bmatrix}_q x^{(a+b+c)+(c+d)} \\ &= 1 + 2x + (q^{-1} + 3 + q)x^2 + (2q^{-2} + 2q^{-1} + 5 + 2q + 2q^2)x^3 + O(x^4), \end{aligned}$$

where the overall factor of $(1-x)$ comes from the elliptic flow loop along the meridian. No framing factors appear, since γ_e and γ_h do not link the knot holder at all, and the sliding factors from ℓ_{pair} cancel: $q^{\frac{\epsilon}{2}} \cdot q^{-\frac{\epsilon}{2}} = 1$.

From the second knot holder on the right of Figure 13, we have:

$$\begin{aligned} \Phi_{S^3 \setminus \mathcal{A}_1}(x, q) &= \sum_{\substack{a,b,c,d,e \geq 0 \\ 0 \leq \epsilon \leq 1}} (-1)^{a+d+b+(b-a+d)} q^{\frac{a^2+d^2-b^2-(b-a+d)^2}{2} + 2\epsilon a - 2\epsilon b} \begin{bmatrix} a+c \\ a \end{bmatrix}_q \begin{bmatrix} a+e \\ d \end{bmatrix}_q \\ &\quad \times \begin{bmatrix} b+e \\ b \end{bmatrix}_{q^{-1}} \begin{bmatrix} b+c \\ a+c-d \end{bmatrix}_{q^{-1}} x^{(a+c)+(a+e)+b+(b-a+d)} (-x^3)^\epsilon \cdot q^{\frac{a+d-b-(b-a+d)}{2} - (a-b)} \\ &= 1 + 2x + (q^{-1} + 3 + q)x^2 + (2q^{-2} + 2q^{-1} + 5 + 2q + 2q^2)x^3 + O(x^4), \end{aligned}$$

where ϵ counts the elliptic flow loop γ_e , and the factor $q^{\frac{a+d-b-(b-a+d)}{2}}$ (resp., $q^{-(a-b)}$) comes from the linking with the framing line γ_h (resp., γ_e).

Observe that they give the same count, which follows from Theorem A. Moreover, they agree with the BPS q -series for the figure-eight knot complement [GM21, Par21]

$$x^{-\frac{1}{2}} \widehat{Z}_{S^3 \setminus \mathcal{A}_1}(x, q) = 1 + 2x + (q^{-1} + 3 + q)x^2 + (2q^{-2} + 2q^{-1} + 5 + 2q + 2q^2)x^3 + O(x^4),$$

which is a special case of Theorem B.

¹⁶This figure-eight knot holder happens to agree with the ‘‘branched covering model’’ from [BW83a].

Remark 3.11. The knot holders encode all the information to determine the full HOMFLYPT-skein-valued flow loop count (i.e., not just its specialization to GL_1 -skeins), where the multiple covers of a primitive flow loop γ is counted by the skein-valued basic annulus partition function [CEL26, Sec. 2.2]

$$w_\gamma := \begin{cases} \sum_\lambda (-1)^{|\lambda|} W_{\lambda, \emptyset} \otimes W_{\emptyset, \lambda^t} & \text{if } \gamma \text{ is elliptic,} \\ \sum_\lambda W_{\lambda, \emptyset} \otimes W_{\emptyset, \lambda} & \text{if } \gamma \text{ is positive hyperbolic,} \\ \sum_\lambda (-1)^{|\lambda|} W_{\lambda, \emptyset} \otimes W_{\emptyset, \lambda} & \text{if } \gamma \text{ is negative hyperbolic.} \end{cases}$$

However, computing such a partition function in practice is unwieldy, as it often requires prior knowledge of all colored HOMFLYPT polynomials of all link types. For instance, even for the figure-eight knot, it is known that all link types appear as periodic orbits [Ghr97]. Hence, the reduction to GL_1 -skeins was crucial for our purposes to have a computable result as in Example 3.10.

3.5. Skein-categorical description. Here we sketch how to extend down (in the sense of TQFT) to surfaces, by rephrasing the flow loop count in terms of skein categories. It will not be used in the rest of this paper, so disinterested readers may safely skip this subsection.

Definition 3.12. Given a surface F equipped with a line field ξ with transverse zeros, its GL_1 -skein category $\mathrm{SkCat}^{\mathrm{GL}_1}(F, \xi)$ is the $\mathbb{Z}[q^{\pm\frac{1}{2}}]$ -linear category where

- Objects are finite number of points on F , away from the zeros of ξ , and
- For each pair of objects $X = \{x_1, \dots, x_k\}$ and $Y = \{y_1, \dots, y_l\}$, the $\mathbb{Z}[q^{\pm\frac{1}{2}}]$ -module of morphisms $\mathrm{Hom}(X, Y)$ is given by the GL_1 -skein module of $F \times [0, 1]$ with framing lines along the zeros of ξ , with boundary conditions given by $X \times \{0\}$ and $Y \times \{1\}$. That is, it is generated by framed¹⁷, oriented tangles in $F \times [0, 1]$ with incoming (resp., outgoing) boundary points at $X \times \{0\}$ (resp., $Y \times \{1\}$) where the framing agrees with ξ , modulo the usual GL_1 -skein relations and the framing line relation.

In the following, we implicitly pass to an appropriate grading completion of the additive closure of the skein category to allow (infinite) direct sums of objects and matrices of morphisms.

Let F be a surface equipped with a marking, as well as a perturbation vector field $\xi = \xi_{\mathrm{pert}}$ adapted to the marking (as in Section 3.3). By a *state* σ on the marked surface F , we mean an assignment of $\sigma(p_i) \in \{0, 1\}$ to each base point p_i and an assignment of $\sigma(\alpha_j) \in \mathbb{Z}_{\geq 0}$ to each arc α_j . Let $\mathcal{S}(F)$ denote the set of all such states. For each state $\sigma \in \mathcal{S}(F)$ on the marked surface F , let X_σ be the object of the skein category $\mathrm{SkCat}^{\mathrm{GL}_1}(F, \xi)$, consisting of $\sigma(\alpha_j)$ distinct interior points of α_j , for each j , together with all the base points p_i for which $\sigma(p_i) = 1$.¹⁸ By taking the formal direct sum over all states, we obtain an object

$$Z(F) := \bigoplus_{\sigma \in \mathcal{S}(F)} X_\sigma \in \mathrm{SkCat}^{\mathrm{GL}_1}(F, \xi).$$

For any self-homeomorphism $\varphi : F \rightarrow F$ preserving the set of base points, as described in Section 3.2, there is a knot holder S in $F \times [0, 1]$ given by the locus of the arcs in the mapping

¹⁷Allowing half-twists as before.

¹⁸The base points p_i are zeros of ξ , so technically, we need to slightly shift these points off the zeros of ξ , but it doesn't matter how we are shifting them off, as the resulting objects are all naturally isomorphic, with the isomorphism given by the tangle consisting of (almost) vertical strands, framed by ξ . For the same reason, it doesn't matter how we choose the $\sigma(\alpha_j)$ interior points of α_j relative to the zero of ξ on α_j .

cylinder of φ , composed with the movie of splitting and joining of the arcs that turns the arcs of $\varphi(F)$ to those of F . Moreover, as described in Section 3.3, there is a perturbation vector field $\xi = \xi_{\text{pert}}$ on $F \times [0, 1]$ adapted to S . Hence, we can perform a state sum on S to obtain a morphism

$$Z(\varphi) : Z(F) \rightarrow Z(F).$$

More precisely, $Z(\varphi)$ is given by a $\mathcal{S}(F) \times \mathcal{S}(F)$ matrix, whose (σ', σ) -entry is the sum of all possible ways to connect the points $\varphi(X_\sigma)$ to the points $X_{\sigma'}$ —where the base points should stay constant, and the points on arcs can follow along the knot holder S —times a sign given by $(-1)^{\text{nh}+\text{e}}$, where nh counts the number of negative hyperbolic flow lines¹⁹, and e counts the inversion number of the partial permutation of the base points used in the states σ and σ' .²⁰

By construction, the assignment $\varphi \mapsto Z(\varphi)$ is functorial, i.e., $Z(\varphi' \circ \varphi) = Z(\varphi') \circ Z(\varphi)$, and we obtain a representation of the mapping class group of F that fixes the set of base points:

$$\text{MCG}(F) \rightarrow \text{Aut}(Z(F)).$$

Moreover, the supertrace²¹ of $Z(\varphi)$,

$$\text{Tr } Z(\varphi) \in \text{Sk}_q^{\text{GL}_1}(M_\varphi, \ell_{\text{fr}}),$$

which is an element of (the action completion of) the GL_1 -skein module of the mapping torus M_φ of φ twisted by framing line ℓ_{fr} along the zeros of ξ , recovers the state sum model on the knot holder discussed in Section 3.4. That is, this is nothing but the GL_1 -skein-valued flow loop count Φ_{M_φ} in M_φ .

4. BRAID GROUP REPRESENTATION ON VERMA MODULES FROM FLOW LOOPS

It turns out that, in the special case when $F = D_n^2$ is a disk with n punctures, we can recover the Lawrence representation [Law90] $L_{n,m}$ of the braid group B_n by counting flow lines on the knot holders associated to braids $\beta \in B_n$.²² Since the Lawrence representation is known to be equivalent to the braid group representation on an appropriate subspace of the tensor products of n copies of Verma modules of the quantum group $U_q(\mathfrak{sl}_2)$, this provides a key connection between the flow loop counts and quantum invariants.

4.1. Braid group representation from knot holders. Let D_n^2 be a disk with n punctures p_1, \dots, p_n which are ordered. Treating the boundary of the disk as a source and the punctures as sinks, we draw a marking on D_n^2 as in Figure 14, by drawing an arc α_i between each pair of neighboring punctures p_i and p_{i+1} . The braid group B_n acts on D_n^2 , and the movie of splitting and joining of the arcs, together with the framing lines, is shown in Figure 15. The resulting knot holder is shown in Figure 16.

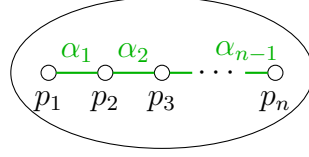
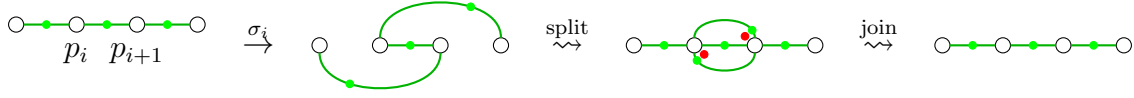
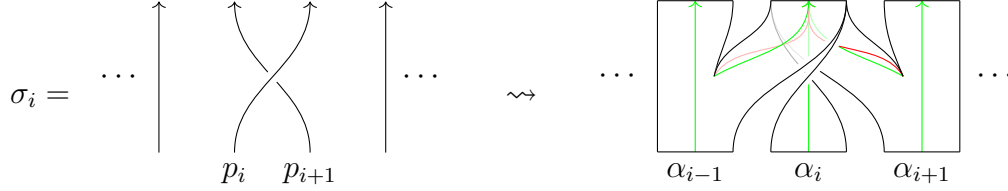
For any nonnegative integer m , let $\mathcal{S}_{n,m}$ denote the set of all ordered $(n-1)$ -tuple of nonnegative integers, (a_1, \dots, a_{n-1}) , such that $\sum_{1 \leq i \leq n-1} a_i = m$. Thinking of a_i as the number of points on the arc α_i , this is just the set of states on D_n^2 consisting of m total

¹⁹Here we are choosing an orientation of the markings, in order to tell which strips of S are half-twisted. The trace of $Z(\varphi)$, however, would be independent of such an orientation choice.

²⁰Here we are using an ordering of the base points. The trace of $Z(\varphi)$, however, would be independent of such an ordering choice.

²¹The $\mathbb{Z}/2$ -grading is given by the parity of the number of base points used in each state. This is to get the appropriate sign for the elliptic flow loops in the mapping torus.

²²This is a special case of the mapping class group representations constructed in Section 3.5.


 FIGURE 14. A disk with n punctures and markings

 FIGURE 15. Action of $\sigma_i \in B_n$ on the markings, together with the framing lines

 FIGURE 16. Knot holder for the Artin generators $\sigma_i \in B_n$. When $i = 1$ (resp., $i = n - 1$), there are no strands to the left (resp., right) of the crossing, so the strips starting from the arc α_{i-1} (resp., α_{i+1}) are not present.

number points. Counting the flow lines on the knot holders above, we obtain a representation of B_n on a vector space with basis labeled by $\mathcal{S}_{n,m}$, which we summarize as a proposition:

Proposition 4.1. *Let $V_{n,m}$ be the $\binom{m+n-2}{m}$ -dimensional vector space with basis $\{v_{\vec{a}}\}_{\vec{a} \in \mathcal{S}_{n,m}}$ labeled by $\mathcal{S}_{n,m}$. Then, the following assignment defines a representation of the braid group B_n on $V_{n,m}$:*

$$\sigma_i \cdot v_{(a_1, \dots, a_{n-1})} = \begin{cases} \sum_{\substack{0 \leq b \leq a_{i-1} \\ 0 \leq c \leq a_{i+1}}} (-1)^{a_i} q^{\frac{a_i^2}{2} + \frac{a_i+b+c}{2}} \begin{bmatrix} a_i + b + c \\ a_i, b, c \end{bmatrix}_q x^{\frac{(a_i+b)+(a_i+c)}{2}} \\ \quad \times v_{(a_1, \dots, a_{i-1}-b, a_i+b+c, a_{i+1}-c, \dots, a_{n-1})} & \text{if } 2 \leq i \leq n-2, \\ \sum_{0 \leq c \leq a_2} (-1)^{a_i} q^{\frac{a_i^2}{2} + \frac{a_i+c}{2}} \begin{bmatrix} a_1 + c \\ c \end{bmatrix}_q x^{\frac{a_i+(a_i+c)}{2}} \\ \quad \times v_{(a_1+c, a_2-c, \dots, a_{n-1})} & \text{if } i = 1, \\ \sum_{0 \leq b \leq a_{n-2}} (-1)^{a_i} q^{\frac{a_i^2}{2} + \frac{a_i+b}{2}} \begin{bmatrix} a_{n-1} + b \\ b \end{bmatrix}_q x^{\frac{(a_i+b)+a_i}{2}} \\ \quad \times v_{(a_1, \dots, a_{n-2}-b, a_{n-1}+b)} & \text{if } i = n-1, \end{cases}$$

where the q -trinomial coefficients are defined by

$$\begin{bmatrix} a+b+c \\ a, b, c \end{bmatrix}_q := \frac{[a+b+c]_q!}{[a]_q! [b]_q! [c]_q!} = \begin{bmatrix} a+b \\ b \end{bmatrix}_q \begin{bmatrix} a+b+c \\ c \end{bmatrix}_q.$$

In the proposition above, the factor $q^{\frac{a_i+b+c}{2}}$ comes from the linking with the framing lines ($q^{\frac{a_i}{2}}$ from linking with γ_h along α_i , and $q^{\frac{b+c}{2}}$ from linking with ℓ_{pair}), and the degree of x counts the linking number with the braid β itself. While we have presented the linking number $\text{lk}(\gamma, \ell_{\text{fr}})$ (resp., $\text{lk}(\gamma, \beta)$) as the average of the signed number of crossings where the flow line γ goes under and over ℓ_{fr} (resp., β), we could have instead only counted the signed number of crossings where γ goes under ℓ_{fr} (resp., β). This will yield an equivalent representation of the braid group, as the linking number remains the same once the braid is closed up. In this equivalent representation, the weight now takes a slightly different form:

$$(-1)^{a_i} q^{\frac{a_i^2}{2} + \frac{a_i}{2} + c} \begin{bmatrix} a_i + b + c \\ a_i, b, c \end{bmatrix}_q x^{a_i+c} = (-1)^{a_i} q^{\frac{a_i(a_i-1)}{2}} \begin{bmatrix} a_i + b + c \\ a_i, b, c \end{bmatrix}_q (qx)^{a_i+c}.$$

Comparing this with the Lawrence representation $L_{n,m}$ written in the basis of “standard code sequences” as in [Mar20, Cor. 4.7]²³, we immediately obtain:

Proposition 4.2. *The braid group representation $V_{n,m}$ in Proposition 4.1 is equivalent to the Lawrence representation $L_{n,m}$.*

Note that, if we fill in the punctures of the disk with elliptic flow lines (and elliptic framing lines along them) and close up, we would be counting the flow loops in the suspension flow of a self-homeomorphism $\beta : D^2 \rightarrow D^2$ specified by the braid β . In other words, it is the flow loop count in the unknot complement $S^3 \setminus O \cong D^2 \times S^1$. But in the unknot complement, there is a much simpler flow with a single elliptic flow loop, so the flow loop count must be $\Phi_{S^3 \setminus O}(z, q) = 1 - z$. Therefore, as a corollary of Theorem A, we have:

Corollary 4.3. *Suppose, for simplicity, that $\beta \in B_n$ is a braid that close up to a knot (i.e., with a single component), and let w denote the writhe of β . Then,*

$$\sum_{\substack{m \geq 0 \\ 0 \leq \epsilon \leq 1}} \text{Tr}_{V_{n,m}}(\beta) \Big|_{x=q^{-1+2\epsilon}} z^m \cdot (q^w)^\epsilon (-z^n)^\epsilon = \Phi_{S^3 \setminus O}(z, q) = 1 - z.$$

In this formula, ϵ counts the elliptic flow loop along the closure of β , the power of z keeps track of the homology class in $D^2 \times S^1 \cong S^3 \setminus O$. In the specialization $x = q^{-1+2\epsilon}$, the factor q^{-1} is from the linking number with the elliptic framing line along the closure of β , and the factor $q^{2\epsilon}$ is from the linking with the elliptic flow loop. Finally, the factor $(q^w)^\epsilon$ is from the linking of the elliptic flow loop with the hyperbolic framing lines.

4.2. Connection to Verma modules. Let $V_\infty(x)$ denote the Verma module of the quantum group $U_q(\mathfrak{sl}_2)$ with generic highest weight $\lambda_x := \log_q x - 1$. Then, the universal R -matrix of $U_q(\mathfrak{sl}_2)$ induces a representation

$$B_n \rightarrow \text{Aut}(V_\infty(x)^{\otimes n}).$$

²³Martel’s t (resp., s) is our q^{-1} (resp., qx).

Explicitly, in some basis v_0, v_1, v_2, \dots of $V_\infty(x)$,

$$\sigma_i \cdot (v_{a_1} \otimes \dots \otimes v_{a_n}) = \sum_{a'_i, a'_{i+1} \geq 0} \check{R}(x)_{a_i, a'_{i+1}}^{a'_i, a'_{i+1}} \cdot v_{a_1} \otimes \dots \otimes v_{a'_i} \otimes v_{a'_{i+1}} \otimes \dots \otimes v_{a_n},$$

where

$$\check{R}(x)_{i,j}^{i',j'} := \delta_{i+j, i'+j'} q^{jj'} (qx^{-1})^{\frac{i+j'+1}{2}} \begin{bmatrix} i \\ j' \end{bmatrix}_q (q^{j+1}x^{-1}; q)_{i-j'}.$$

Let $(V_\infty(x)^{\otimes n})_m$ denote the $q^{\frac{n\lambda_x}{2}-m}$ -weight subspace of $V_\infty(x)^{\otimes n}$, i.e., the span of basis vectors $v_{a_1} \otimes \dots \otimes v_{a_n}$ for which $a_1 + \dots + a_n = m$. By restricting the braid group representation to this weight subspace and further restricting to the space of null vectors

$$N_{n,m} := \ker E \cap (V_\infty(x)^{\otimes n})_m$$

in that weight subspace, we obtain a subrepresentation of dimension $\binom{m+n-2}{m}$.

Kohno's theorem [Koh12], as reviewed in [Ito15, Sec. 4.2], proves that this subrepresentation $N_{n,m}$ is equivalent to the Lawrence representation $L_{n,m}$. Since

$$(V_\infty(x)^{\otimes n})_m = \bigoplus_{0 \leq k \leq m} F^{m-k} N_{n,k} \cong \bigoplus_{0 \leq k \leq m} N_{n,k},$$

we can express the graded trace of the braid group representation on $V_\infty(x)^{\otimes n}$ in terms of the graded trace of Lawrence representations, or of $V_{n,m}$ using Proposition 4.2; this proves Theorem C. In the convention we have been using, we can summarize this as:

Theorem 4.4. *The graded trace of the braid group representation on $V_\infty(x^{-1})^{\otimes n}$ can be expressed in terms of flow loop counts:*

$$\sum_{m \geq 0} \text{Tr}_{(V_\infty(x^{-1})^{\otimes n})_m}(\beta) z^m = (qx)^{\frac{w}{2}} \frac{1}{1-z} \sum_{m \geq 0} \text{Tr}_{V_{n,m}}(\beta) z^m,$$

where both sides are elements of $\mathbb{Z}[q^{\pm \frac{1}{2}}, x^{\pm \frac{1}{2}}][[z]]$.

As an application of Kohno's theorem, Ito [Ito19, Thm. 3.1] showed that the MMR expansion of a knot K , presented as the closure of a braid β , can be expressed in terms of the traces of the Lawrence representation applied to β . Using Proposition 4.2, we rewrite Ito's theorem in terms of the representations $V_{n,m}$:²⁴

Theorem 4.5. *Given a knot K presented as the closure of a braid β with n strands and writhe w ,*

$$(x^{\frac{1}{2}} - x^{-\frac{1}{2}}) \text{MMR}_K(\hbar, x) = -q^{\frac{w-(n-1)}{2}} x^{\frac{w-n}{2}} \sum_{m \geq 0} (1 - q^{2m+(n-1)} x^n) \cdot q^{-m} \text{Tr}_{V_{n,m}}(\beta).$$

In fact, this follows formally from Theorem 4.4:

$$\begin{aligned} -\frac{x^{\frac{1}{2}} - x^{-\frac{1}{2}}}{q^{\frac{1}{2}} - q^{-\frac{1}{2}}} \text{MMR}_K(\hbar, x) &= \sum_{m \geq 0} \text{Tr}_{(V_\infty(x^{-1})^{\otimes n})_m}(\beta) \left((x^{-\frac{1}{2}} q^{-\frac{1}{2}})^n q^{-m} + (x^{\frac{1}{2}} q^{\frac{1}{2}})^n q^m \right) \\ &\stackrel{\text{Thm. 4.4}}{=} (qx)^{\frac{w}{2}} \left(\frac{(qx)^{-\frac{n}{2}}}{1-q^{-1}} \sum_{m \geq 0} \text{Tr}_{V_{n,m}}(\beta) q^{-m} + \frac{(qx)^{\frac{n}{2}}}{1-q} \sum_{m \geq 0} \text{Tr}_{V_{n,m}}(\beta) q^m \right) \end{aligned}$$

²⁴Ito's z is our x^{-1} .

$$= \frac{q^{\frac{1}{2}}(qx)^{\frac{w-n}{2}}}{q^{\frac{1}{2}} - q^{-\frac{1}{2}}} \sum_{m \geq 0} (1 - q^{2m+(n-1)}x^n) \cdot q^{-m} \text{Tr}_{V_{n,m}}(\beta).$$

Remark 4.6. One needs to be a little careful about the meaning of the right-hand side of Theorem 4.5, as it does not in general converge as a power series in x , x^{-1} or $(1-x)$. Instead, it should be regarded as an element of $\mathbb{Q}(x^{\frac{1}{2}})[[\hbar]]$, using the fact that, in the classical limit, $V_{n,m}|_{q=1} \cong \text{Sym}^m V_{n,1}|_{q=1}$, and that

$$x^{\frac{w}{2}} \frac{x^{\frac{n}{2}} - x^{-\frac{n}{2}}}{x^{\frac{1}{2}} - x^{-\frac{1}{2}}} \sum_{m \geq 0} \text{Tr}_{\text{Sym}^m V_{n,1}}(\beta)|_{q=1} = x^{\frac{w}{2}} \frac{x^{\frac{n}{2}} - x^{-\frac{n}{2}}}{x^{\frac{1}{2}} - x^{-\frac{1}{2}}} \frac{1}{\det(I - V_{n,1}(\beta)|_{q=1})} = \frac{1}{\Delta_K(x)}.$$

That the coefficients of the higher \hbar -degree terms can also be resummed into rational function in x can be shown analogously to Rozansky’s proof [Roz98] of the MMR conjecture. That is, one can consider a random walk model (i.e., a Markov chain) whose states are the strips of the knot holder for β and whose transition probability from a strip s to another strip s' can be non-zero iff s' can directly follow s along the semiflow on the knot holder. For each such pair (s, s') of strips, we associate an independent parameter as the transition probability.²⁵ By Foata–Zeilberger formula [FZ99] (see also [LW01] for an exposition), the result of this parametrized state sum is given by $\frac{1}{\det(I-\mathcal{B})}$ where \mathcal{B} denotes the transition matrix of the Markov chain, and specialization of the parameters to appropriate monomials of the form $\pm x^{\dots}$ (according to the classical limit of the state sum on the knot holder) recovers $\frac{1}{\Delta_K(x)}$. The higher \hbar -degree terms can be obtained by applying an appropriate differential operators (in the parameters) to $\frac{1}{\det(I-\mathcal{B})}$ before specializing the parameters, in the same manner as in Rozansky’s proof of the MMR conjecture.²⁶ It follows that the coefficients of the higher \hbar -degree terms are also rational functions in x .

5. QUANTUM GROUP INVARIANTS FROM FLOW LOOPS

In this section, we prove Theorem B.

Lemma 5.1. *Theorem B holds for all braid-positive knots.*

Proof. If a knot K is the closure of a positive braid β with n strands and w number of crossings, then the corresponding knot holder \mathcal{H}_K constructed in Example 3.8 is the same as the knot holder \mathcal{H}_β for the braid β constructed in Section 4.1, but now with an elliptic flow loop and an elliptic framing line along the braid axis. It follows that the flow loop count is

$$\begin{aligned} \Phi_{S^3 \setminus K}(x, q) &= \sum_{\substack{m \geq 0 \\ 0 \leq \epsilon \leq 1}} q^{2\epsilon m} \text{Tr}_{V_{n,m}}(\beta) (-x^n)^\epsilon \cdot q^{\epsilon(n-1)-m} \\ &= \sum_{m \geq 0} (1 - q^{2m+(n-1)}x^n) \cdot q^{-m} \text{Tr}_{V_{n,m}}(\beta), \end{aligned}$$

where ϵ counts the elliptic flow loop along the braid axis, the factor $q^{2\epsilon m}$ is from the linking between elliptic and hyperbolic flow loops, $q^{\epsilon(n-1)}$ is from the linking of the elliptic flow loop

²⁵We treat those parameters as independent, formal variables and do not impose the condition that the sum of all transition probabilities from a given state is 1.

²⁶In fact, it is easier in our case, as our state sum on knot holder only involves monomials and q -binomials, so all we need is [Roz98, Lem. A.1] which gives the perturbative expansion of q -binomials.

with the the hyperbolic framing lines, and q^{-m} is from the linking of the hyperbolic flow loops with the elliptic framing line along the braid axis.

Comparing with Theorem 4.5, we see that this agrees (up to a monomial factor) with the MMR expansion. As shown in [Par20], this MMR expansion can be resummed in a unique way into a power series in q and x , which gives the BPS q -series $\widehat{Z}_{S^3 \setminus K}(x, q)$. Therefore,

$$\Phi_{S^3 \setminus K}(x, q) = -q^{\frac{(n-1)-w}{2}} x^{\frac{n-w}{2}} \widehat{Z}_{S^3 \setminus K}(x, q)$$

as desired. \square

In the rest of this section, we will extend this result to all braid-homogeneous knots. The idea of proof is very similar to that of the *inverted state sum* introduced in [Par21].

Proof of Theorem B. Let K be a knot which is the closure of a homogeneous braid β . Let \mathcal{H}_β denote the knot holder for braid β constructed in Section 4.1 and \mathcal{H}_K denote the knot holder for K constructed in Example 3.8. Note that \mathcal{H}_β is in general *not* a knot holder for the flow on the fibered knot complement $S^3 \setminus K$.

Starting from the right-hand side of Theorem 4.5, which is a state sum on \mathcal{H}_β (together with an extra elliptic flow loop and an elliptic framing line along the braid axis), we will “invert” all the states on the columns of strips corresponding to negative crossings. We will then observe that this inverted state sum on \mathcal{H}_β can be naturally identified (up to some monomial) with the state sum on the actual knot holder \mathcal{H}_K for the fibered knot complement $S^3 \setminus K$.

Step 1: Inverted state sum on \mathcal{H}_β . Let γ_e denote the braid axis of β where we place both the elliptic flow loop and an elliptic framing line. The right-hand side of Theorem 4.5 is the state sum

$$Z_\beta(\hbar, x) := -q^{\frac{w-(n-1)}{2}} x^{\frac{w-n}{2}} \sum_{\sigma \in \mathcal{S}(\mathcal{H}_\beta, \gamma_e)} w(\sigma),$$

where, as in Section 3.4, $\mathcal{S}(\mathcal{H}_\beta, \gamma_e)$ denotes the set of all states, so that $\sigma \in \mathcal{S}(\mathcal{H}_\beta, \gamma_e)$ assigns a nonnegative integers to each strip of \mathcal{H}_β and either 0 or 1 to γ_e . As discussed briefly in Remark 4.6, this state sum should be understood in terms of its perturbative expansion, as an element of $\mathbb{Q}(x^{\frac{1}{2}})[[\hbar]]$.

Define the set of inverted states $\mathcal{S}^{\text{inv}}(\mathcal{H}_\beta, \gamma_e)$ in the same was as the usual states $\mathcal{S}(\mathcal{H}_\beta, \gamma_e)$, except that for the strips on the columns of negative crossings, we assign (strictly) negative integers instead of the usual nonnegative integers. Define the corresponding inverted state sum to be

$$Z_\beta^{\text{inv}}(\hbar, x) := -q^{\frac{w-(n-1)}{2}} x^{\frac{w-n}{2}} \sum_{\sigma \in \mathcal{S}^{\text{inv}}(\mathcal{H}_\beta, \gamma_e)} w(\sigma),$$

where the weights $w(\sigma)$ of the inverted states are defined in the same way as before.²⁷ The following lemma allows us to pass to the inversion.

Lemma 5.2. *The inversion preserves the state sum up to a sign:*

$$Z_\beta(\hbar, x) = (-1)^{\text{col}_-} Z_\beta^{\text{inv}}(\hbar, x)$$

where both sides are elements of $\mathbb{Q}(x^{\frac{1}{2}})[[\hbar]]$, and col_- denotes the number of columns of negative crossings in the homogeneous braid β .

²⁷The integers that a state σ assigns appear in power of (-1) , q , and x , as well as in q -binomials in the weight $w(\sigma)$, and they all have natural extension to all (not just nonnegative) integers.

Proof. The proof is completely analogous to the proof of [Par21, Thm. 1], so we will be concise and just give a sketch here.

Firstly, the differential operators on the parameters that give rise to the higher \hbar -degree terms (as in Rozansky's proof [Roz98] of MMR conjecture) remain the same before and after the inversion; see e.g., [Par26, Lem. A.3]. It follows that it is enough to prove the statement in the classical limit but with parameters.

In the classical limit, we need to compare $\frac{1}{\det(I-\mathcal{B})}$ with $\frac{1}{\det(I-\mathcal{B}_{\text{inv}})}$ times some monomial in the parameters, where \mathcal{B}_{inv} denotes the transition matrix of the inverted random walk model. Both $\det(I-\mathcal{B})$ and $\det(I-\mathcal{B}_{\text{inv}})$ can be interpreted as the signed sum of simple multi-cycles in the respective random walk models, and there is a bijection between these simple multi-cycles: For any simple multi-cycle in the original random walk model, we simply flip the used and unused strips along all the inverted columns, to get a simple multi-cycle in the inverted random walk model; c.f., [Par21, Fig. 8]. Under this bijection, we get some extra monomial factor which cancels the monomial factor up to sign, and the sign is given exactly by $(-1)^{\text{col-}}$. The lemma follows. \square

This lemma shows that the inverted state sum, with the extra sign, has the same perturbative series as the MMR expansion. Moreover, this inverted state sum converges in the two-variable power series ring $(x^{\frac{1}{2}} - x^{-\frac{1}{2}})\mathbb{Z}[q^{\pm 1}][[x]]$. It immediately follows that it must be equal to the BPS q -series, as defined in [Par21].

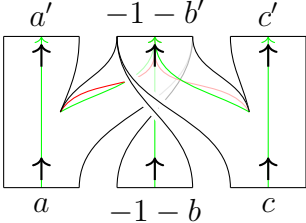
Corollary 5.3. *For any braid-homogeneous knot K ,*

$$\widehat{Z}_{S^3 \setminus K}(x, q) = (-1)^{1+\text{col-}} q^{\frac{w-(n-1)}{2}} x^{\frac{w-n}{2}} \sum_{\sigma \in \mathcal{S}^{\text{inv}}(\mathcal{H}_\beta, \gamma_e)} w(\sigma),$$

where both sides are elements of $(x^{\frac{1}{2}} - x^{-\frac{1}{2}})\mathbb{Z}[q^{\pm 1}][[x]]$.

Step 2: Identification with the state sum on \mathcal{H}_K . It remains to show that the right-hand side of Corollary 5.3 actually computes the state sum on the knot holder \mathcal{H}_K from Example 3.8, up to some monomial factor.

The key observation is the following identity which relates the weight in the inverted state sum on \mathcal{H}_β with the weight in the state sum on \mathcal{H}_K :



$$\begin{aligned} &= \delta_{a+(-1-b)+c, a'+(-1-b')+c'} (-1)^{-1-b} q^{-\frac{(-1-b)^2+(-1-b')}{2}} \left[a - a', -1 - b, c - c' \right]_{q^{-1}} x^{-\frac{(-1-b)+(-1-b')}{2}} \\ &= -x \cdot \delta_{a+b'+c, a'+b+c'} (-1)^{b'} q^{-\frac{b'^2+b}{2}} \left[a - a', b', c - c' \right]_{q^{-1}} x^{\frac{b+b'}{2}} \end{aligned}$$

$$= -x \cdot q^{\frac{b'-b}{2}}$$

Since we are inverting a whole column of strips, the product of the factors $q^{\frac{b'-b}{2}}$ will cancel, but the factor $(-x)$ will survive, one for each negative crossing.

On top of this, for each inverted column, we need to compare the contributions from the linking between

- (1) hyperbolic flow loops (in that column) and elliptic flow loop,
- (2) hyperbolic flow loops (in that column) and elliptic framing line, and
- (3) hyperbolic framing line (in that column) and elliptic flow loop.

Suppose b is the nonnegative integer that a state on \mathcal{H}_K assigns to a strip at the bottom of a column of negative crossings. Then the product of the contributions listed above in the state sum on \mathcal{H}_K is given by

$$q^{-2cb} \cdot q^b \cdot q^{-\epsilon}.$$

On the other hand, the corresponding inverted state on \mathcal{H}_β would assign the negative integer $-1 - b$ to that strip, and the product of the contributions listed above in the inverted state sum on \mathcal{H}_β is given by

$$q^{2\epsilon(-1-b)} \cdot q^{-(-1-b)} \cdot q^\epsilon = (q^{-2cb} \cdot q^b \cdot q^{-\epsilon}) \cdot q.$$

That is, it is q times the one in \mathcal{H}_K , and hence there is an extra factor of q for each inverted column.

Putting everything together, we conclude, as desired, that

$$\begin{aligned} \widehat{\mathcal{Z}}_{S^3 \setminus K}(x, q) &= (-1)^{1+\text{col}_-} q^{\frac{w-(n-1)}{2}} x^{\frac{w-n}{2}} \sum_{\sigma \in \mathcal{S}^{\text{inv}}(\mathcal{H}_\beta, \gamma_e)} w(\sigma) \\ &= (-1)^{1+\text{col}_-} q^{\frac{w-(n-1)}{2}} x^{\frac{w-n}{2}} \cdot (-x)^{\text{cr}_-} q^{\text{col}_-} \Phi_{S^3 \setminus K}(x, q) \\ &= (-1)^{1+\text{cr}_- + \text{col}_-} q^{\frac{w-(n-1)}{2} + \text{col}_-} x^{\frac{w-n}{2} + \text{cr}_-} \Phi_{S^3 \setminus K}(x, q) \\ &= (-1)^{1+\lambda} q^{g-\lambda} x^{-\frac{1}{2}+g} \Phi_{S^3 \setminus K}(x, q), \end{aligned}$$

where cr_- denotes the total number of negative crossings in β , and g is the Seifert genus of K , and λ is the Hopf invariant (a.k.a. enhanced Milnor invariant [Rud87]) of K .²⁸ □

As a quick sanity check, note that this is consistent with our previous computation on trefoil and the figure-eight knots in Examples 3.9 and 3.10.

²⁸The appearance of the Hopf invariant λ in the exponent of q in the leading term of the BPS q -series was observed previously by [OSSAS26].

APPENDIX A. ELEMENTARY PROOF OF INVARIANCE UNDER BIFURCATIONS

In a generic 1-parameter family of a circle-valued Morse function and a metric, there are five types of bifurcations that may occur, as listed in [Hut02, Sec. 1.7]. However, since we are only interested in circle-valued Morse functions without any critical points (and 1-parameter families through such Morse functions), the only bifurcation that may occur is a degenerate closed orbit, which includes two possibilities:

- (1) simple creation/annihilation of closed orbits,
- (2) period-doubling bifurcation.

The invariance of the GL_1 -skein-valued flow loop count will follow from simple q -series identities.

- (1) **Simple creation/annihilation (a.k.a. saddle-node bifurcation):** Under this bifurcation, a positive hyperbolic flow loop and an elliptic flow loop may be created or annihilated in pairs. Before turning on q , this corresponds to the identity

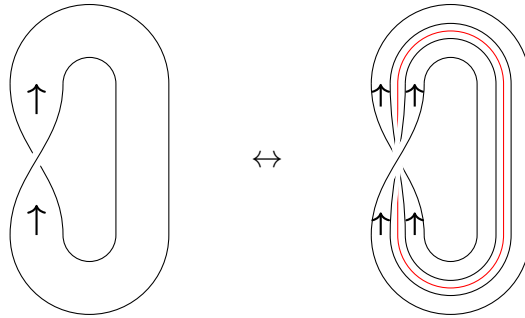
$$1 = \frac{1 - x}{1 - x}.$$

After turning on q , the invariance follows from the following q -series identity:

$$1 = \sum_{\substack{n_{h_+} \geq 0 \\ 0 \leq n_e \leq 1}} q^{f(n_{h_+} + n_e)^2} x^{n_{h_+}} (-x)^{n_e},$$

where f is the framing of the flow loops and x is the homology class.

- (2) **Period-doubling bifurcation:** Under this bifurcation, a negative hyperbolic flow loop may turn into an elliptic flow loop, together with a positive hyperbolic flow loop of twice the period.²⁹ In terms of knot holders, this can be visualized as splitting of Möbius band, while creating an elliptic flow loop:



Before turning on q , this corresponds to the identity

$$\frac{1}{1 + x} = \frac{1 - x}{1 - x^2}.$$

After turning on q , the invariance follows from the following q -series identity:

$$\sum_{n_{h_-} \geq 0} q^{fn_{h_-}^2} (-x)^{n_{h_-}} = \sum_{\substack{n_{h_+} \geq 0 \\ 0 \leq n_e \leq 1}} q^{f(2n_{h_+} + n_e)^2} (x^2)^{n_{h_+}} (-x)^{n_e},$$

where f is the (half-integer) framing and x is the homology class.

²⁹There is also a version for $1 - x = \frac{1-x^2}{1+x}$, but it is analogous.

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DEPARTMENT OF MATHEMATICS & CENTER OF MATHEMATICAL SCIENCES AND APPLICATIONS, HARVARD UNIVERSITY, CAMBRIDGE, MA 02138, USA

Email address: sunghyukpark@math.harvard.edu